



國家同步輻射研究中心  
*National Synchrotron Radiation Research Center*

# Design Status of the TPS Control System

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NSRRC



# Taiwan Photon Source - Major Parameters

<b>Circumference C (m)</b>	<b>518.4</b>
<b>Energy E (GeV)</b>	<b>3.0</b>
<b>Natural emittance <math>\epsilon_{x0}</math> (nm-rad)</b>	<b>1.6</b>
<b>Revolution period (ns)</b>	<b>1729.2</b>
<b>Revolution frequency (kHz)</b>	<b>578.30</b>
<b>Radiofrequency (MHz)</b>	<b>499.654</b>
<b>Harmonic number h</b>	<b>864</b>
<b>SR loss per turn (dipole) (MeV)</b>	<b>0.85269</b>
<b>Betatron tune <math>\nu_x/\nu_y</math></b>	<b>26.18 / 13.28</b>
<b>Momentum compaction (<math>\alpha_1, \alpha_2</math>)</b>	<b><math>2.4 \times 10^{-4}, 2.1 \times 10^{-3}</math></b>
<b>Natural energy spread <math>\sigma_E</math></b>	<b><math>8.86 \times 10^{-4}</math></b>
<b>Damping partition <math>J_x/J_y/J_s</math></b>	<b>0.9977/1.0/ 2.0023</b>
<b>Damping time <math>\tau_x/\tau_y/\tau_s</math> (ms)</b>	<b>12.20/ 12.17 / 6.08</b>
<b>Natural chromaticity <math>\xi_x/\xi_y</math></b>	<b>-75 / -26</b>
<b>Dipole bending radius <math>\rho</math>(m)</b>	<b>8.40338</b>



# Taiwan Photon Source Site Bird View

*Total budget: ~ 200 Million USD*

*Schedule:*

*Most probably groundbreaking date: before the end of this year*

*Commissioning start in late 2013*

TLS Booster Synchrotron

TLS Storage Ring

TPS Storage Ring &  
Booster Synchrotron

User ADM Center



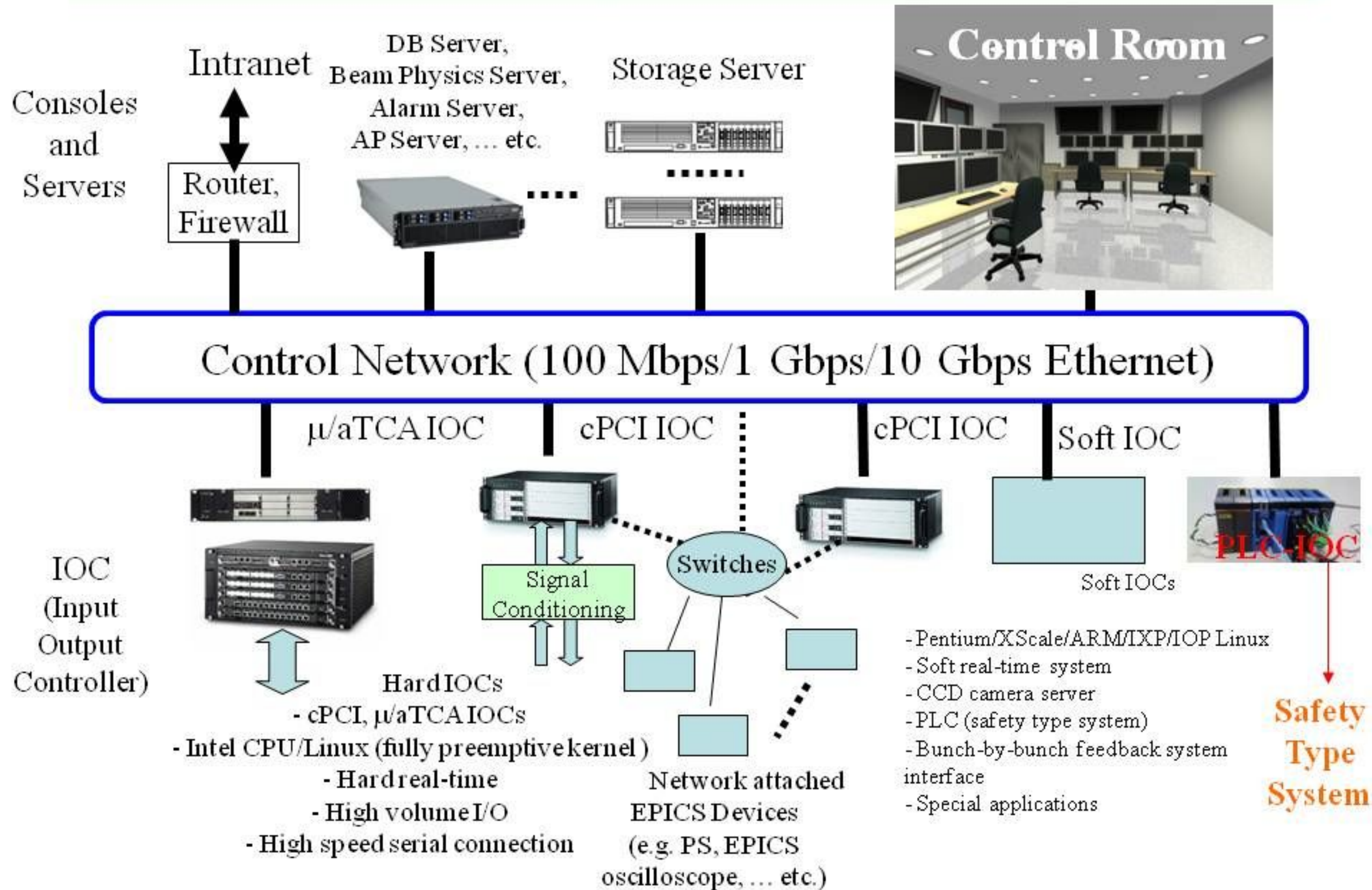


# Technical Selection for the TPS Control System

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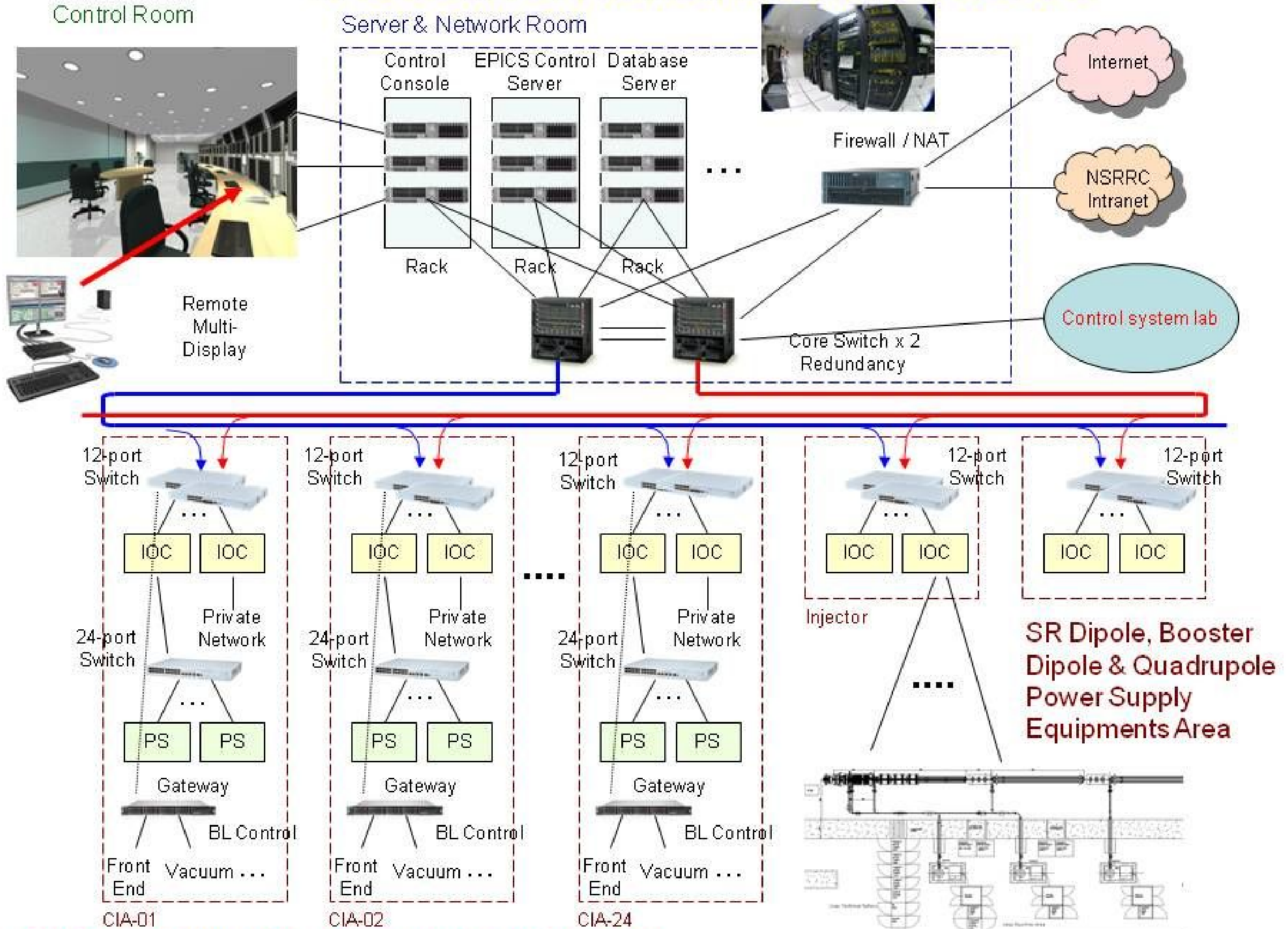
- Control system framework => EPICS toolkit.
- Budget and support consideration:  
Acquire as many of parts from local vendors as possible  
=> Adopt cPCI,  $\mu$ /aTCA, and other embedded solutions  
for IOC layer.
- Borrow available resources from other labs.
- Adopt updated products which will not phase out soon.
- Limited manpower limit too much development.  
Adopt available resources as possible.  
Only limited development is possible.

# TPS Control System Infrastructure



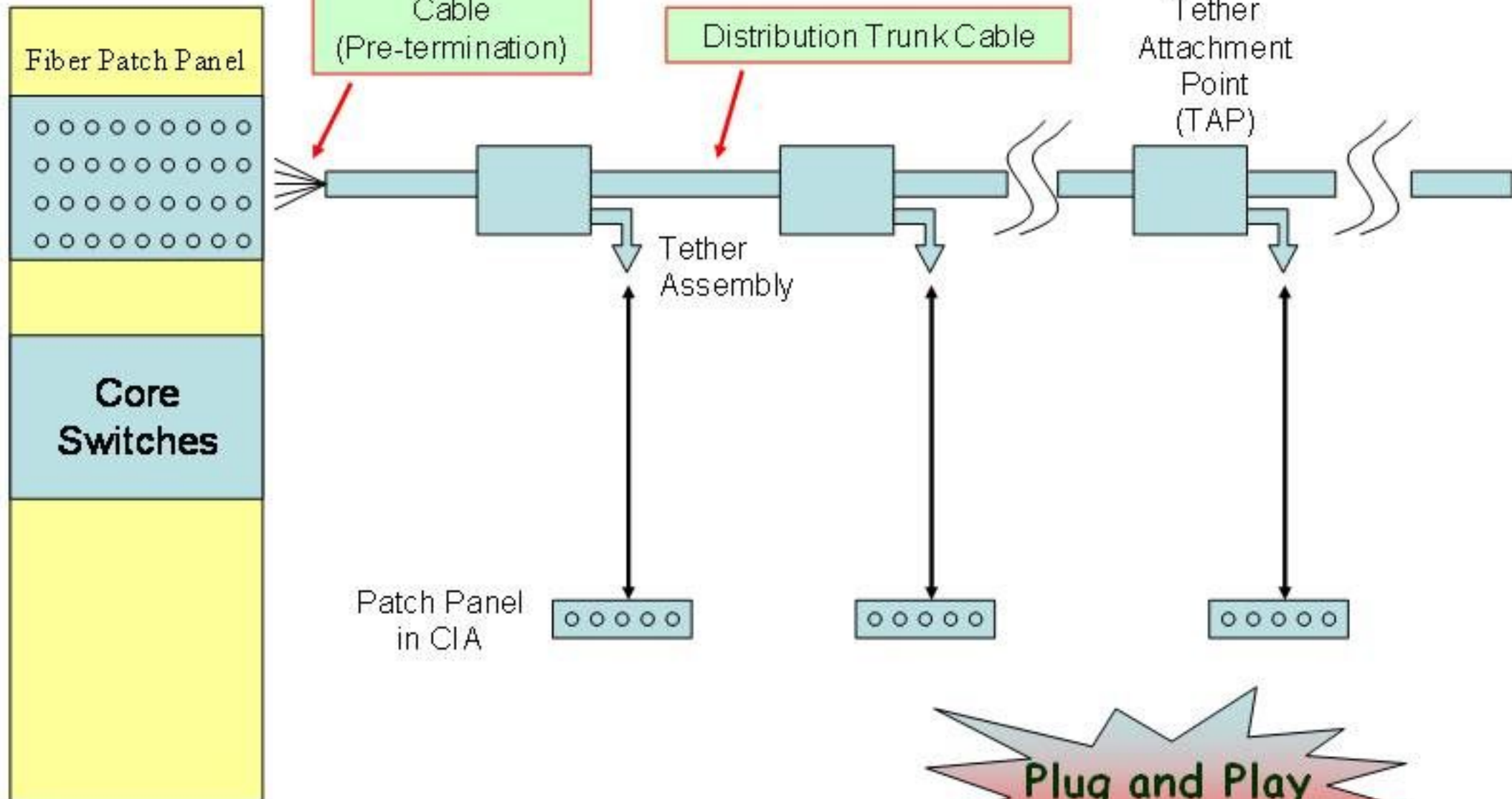


# TPS Control Network Infrastructure



# Modular Cabling System

Control System  
Computer/  
Network Room





# Hardware Building Blocks @ EPICS IOC Level

CompactPCI IOC  
(Linux)



cPCI CPU board



128 Bits DI/DO



ADC/DAC



EVG, EVR in 6 U cPCI  
form factor

BI, BO, AI, AO, Timing,  
Network attached devices

ACQ IOC  
(Linux)



Intel IOP + ADC



16 bits, 96 Channels  
24 Bits, 64 Channels

Analog Reading  
10 Hz rate and 10 KHz rate

$\mu$ /aTCA IOC

and

Feedback Platform

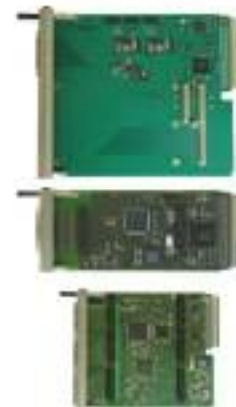
(Linux, Realtime Linux, FPGA)



AMC Module



Carrier Module



Special Applications



Compute Blade



Switch Blade



Carrier Blade



PLC Embedded  
EPICS IOC



Libera IOC  
(Intel XScale, Linux)



Scope IOC



Network attached devices





# Control Console Solution - Remote Multi-display Graphics

Remote multi-display graphics for human being comfortable environments with 24/7/365 :

- Improve control systems maintenance and life cycle support
- Climate and noise control for console consoles
- Better workspace management and ergonomics

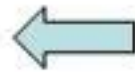
Noise reduction

Save space

Don't need consider thermal problem

Slightly expensive

Server Room



Control Room

Better Cooling



up to 250 m (820 ft)



# Interface Standard

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- cPCI crate
  - Low cost, high performance and reliable cPCI system.
  - Redundant and hot swappable crate power supplies.
  - Remote crate management.
- cPCI I/O modules
  - 32/64 channel 24 bits ADC (with transient signal capture capability, D-tACQ)
  - 16/32 channel 18 bits DAC (D-tACQ)
  - 128 bit DI, 128 bit DO (ADlink)
  - Timing solution: EVG, EVR (cPCI & PMC form factor, MRF)
  - In house designed electrical/optical fanout, patch panels
- aTCA crates system
  - Network attached devices
  - Fast feedback
- Fast waveform capture : Scope IOC, LXI oscilloscope
- Camera (diagnostic): GigE Vision



# Interface Standard - cont.

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- Ethernet and LXI Compliant devices

  - Power supply

  - Diagnostics

  - LXI oscilloscope

  - DMM

  - Temperature monitor

    - ... etc.

- Motion control: Ethernet based motion controller

- PLC solution

  - S7/300 PLC testbed: turnkey system from EU  
(Siemens or VIPA)

  - Yokogawa M3R PLC embedded EPICS IOC

  - Safety PLC (selected by the safety group)

- RS-232C/422/485 devices

  - Ethernet to RS-232/422/482 serial device servers or IOC



# Power Supply Control Interface

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- Large (Digital regulator)
  - Ethernet interface
  - ENOB > 18 bits
  - Communication protocol is still pending
- Medium power supply
  - Ethernet interface
  - ENOB > 18 bits
  - Communication protocol is still pending
- Booster synchrotron large and medium power supply
  - Ethernet interface with waveform capability
- Small power supply (analogue power supply)
  - Analog interface (18 or 24 bits)
  - cPCI 18 bits DAC

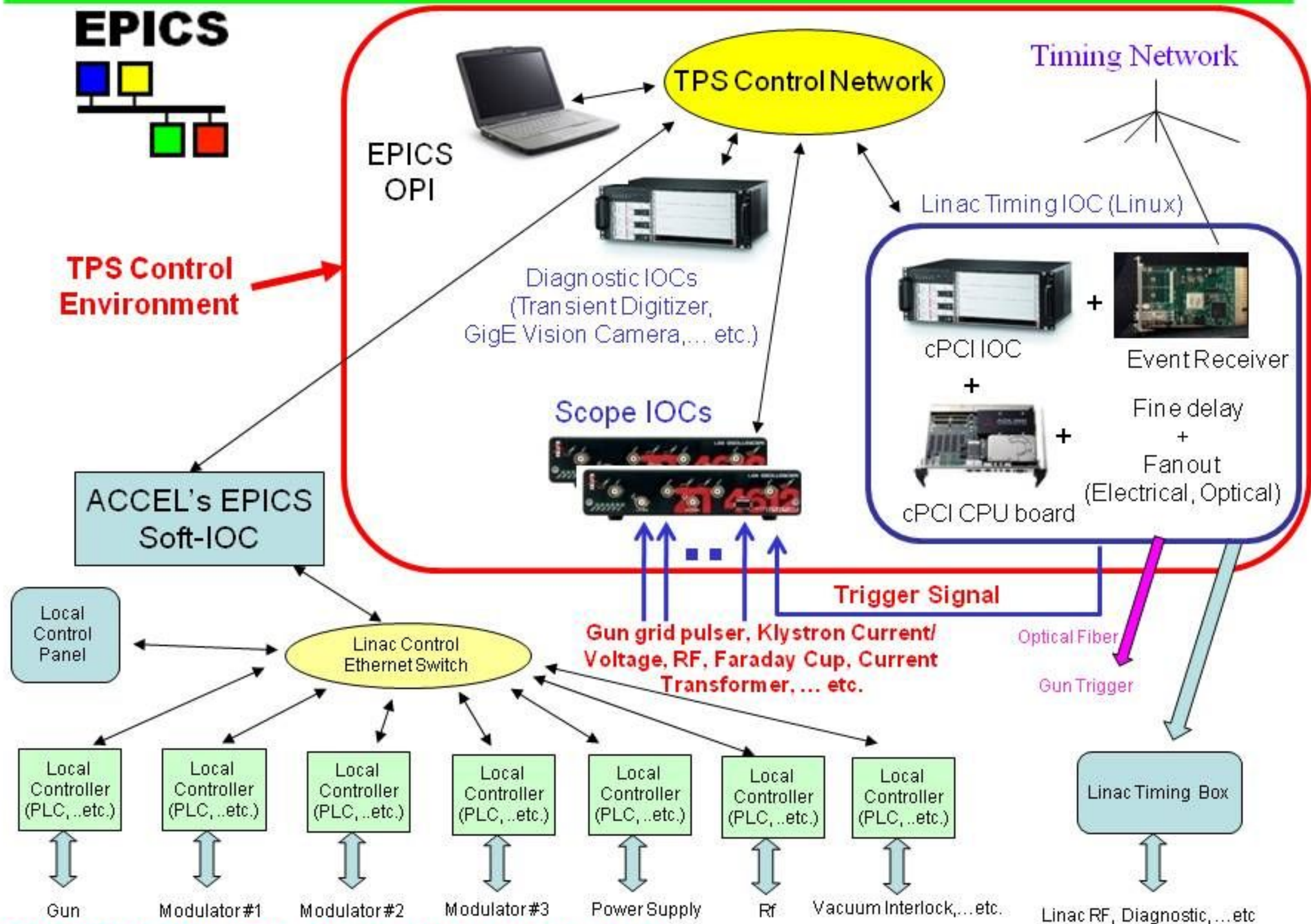
# Turnkey System Interface

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- Turnkey systems compliant with EPICS based controls.
- Turnkey systems include:
  - Linac (contracted out in December 2008)
  - RF transmitter (contracted out in December 2008)
  - Outsource insertion devices
  - Monochromator and other beamline components
  - ... etc.
- Possible turnkey EPICS devices included:
  - BPM electronics, Scope IOC, ...
- Minimize workload of integration and maintenance
  - Standard components should be chosen to get consistency of hardware
  - Provide EPICS development environment and documentation
  - Follow TPS PV name convention

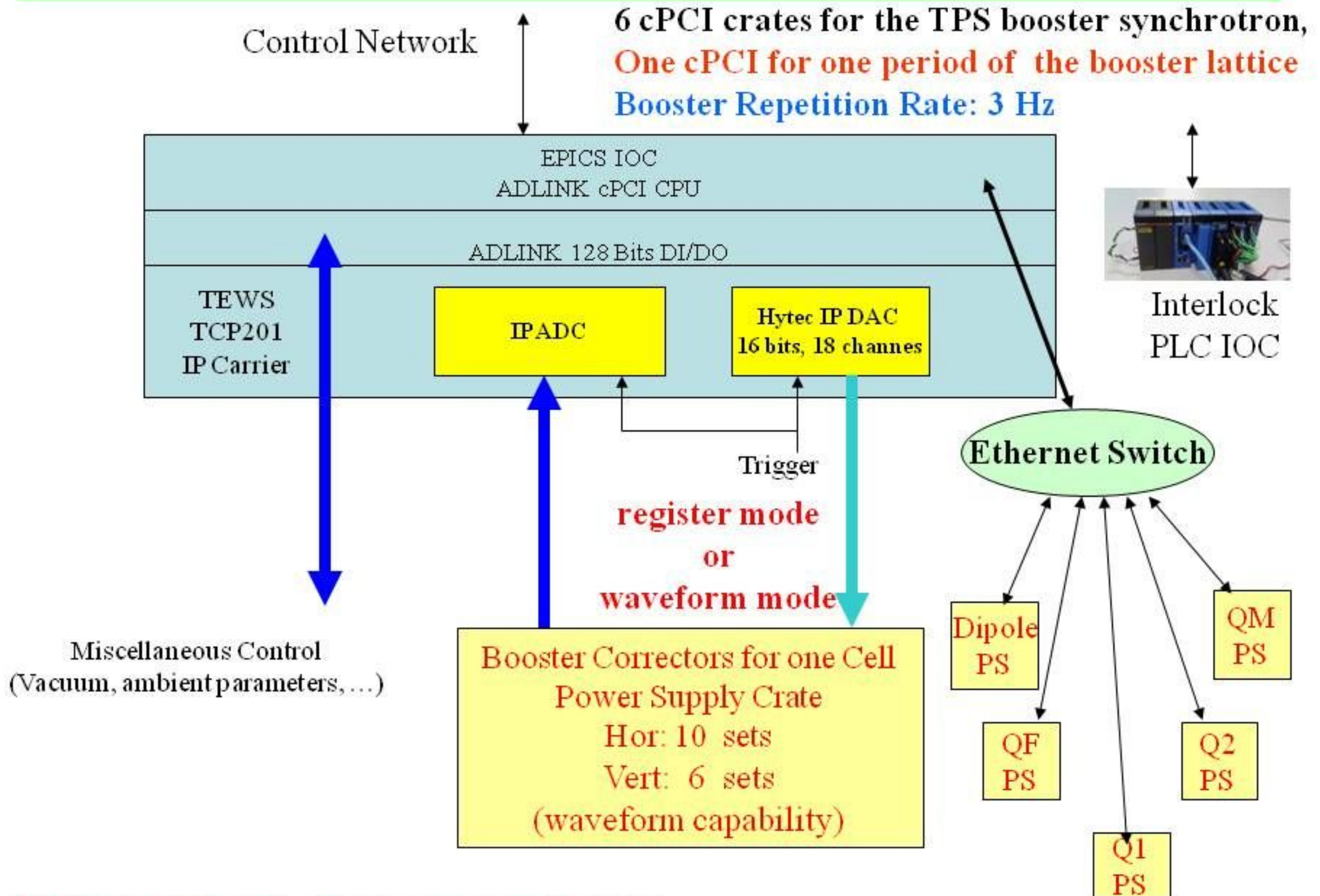


# Linac System Control Environment





# Booster Synchrotron Control Environment





# Timing Solution

## TPS Event System (MRF)

cPCI6U-EVG-300  
(in develop)



cPCI6U-EVR-300  
(in develop)

cPCI6U-EVRTG-300  
(= VME EVR230 + GUN-TX  
+ GUN-RX + 4TIMD )  
(in develop)

Hardware will available in late 2010

## Prototype system

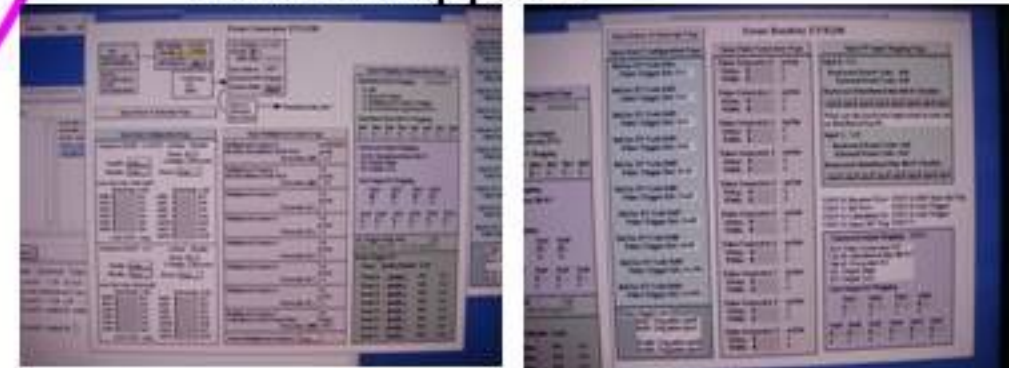


cPCI-EVG-230



cPCI-EVR-230

Develop EPICS Device and  
Driver Supports



Simple Configure Page

# Miscellaneous System Interface

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- Vacuum system
  - BI, BO, AI, AO, serial links, ..etc.
- Diagnostics
  - BPM electronics: Ethernet.
  - BI, BO, AI, AO, counter
- Machine protection
  - Dedicated PLC system with fast link
  - Ethernet to control system.
- Personnel protection
  - Dedicated PLC system with fast link
  - Ethernet to control system.

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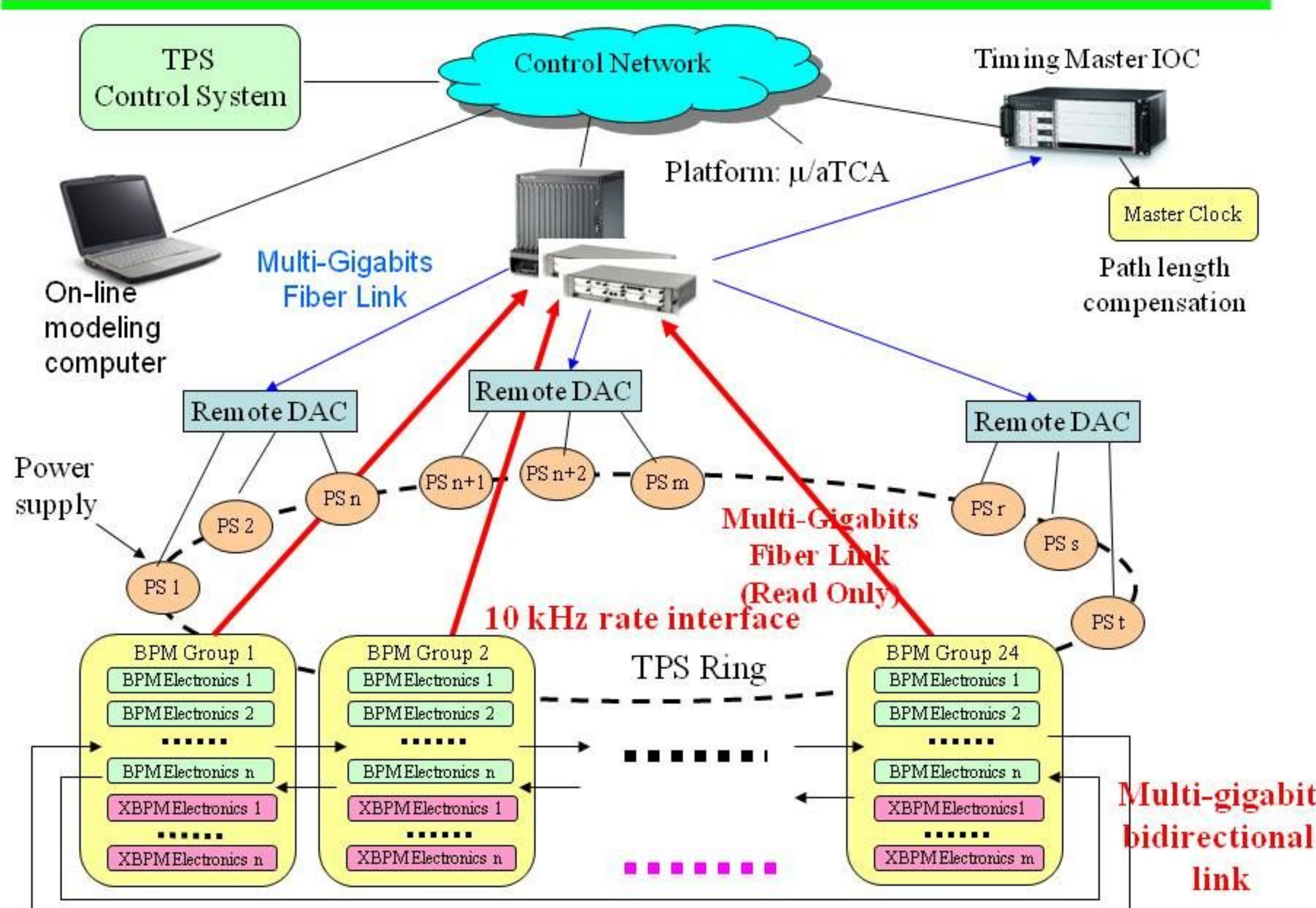


# Proposed Infrastructure for the TPS Orbit Feedback

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- Global orbit feedback loop combined with slow and fast corrector
- xTCA platform
- Prefer to FPGA based system
- Fast BPM data transportation  
Gigabit ethernet Libera Grouping or DiamondCC or another scheme
- Corrector control  
Remote high resolution DAC

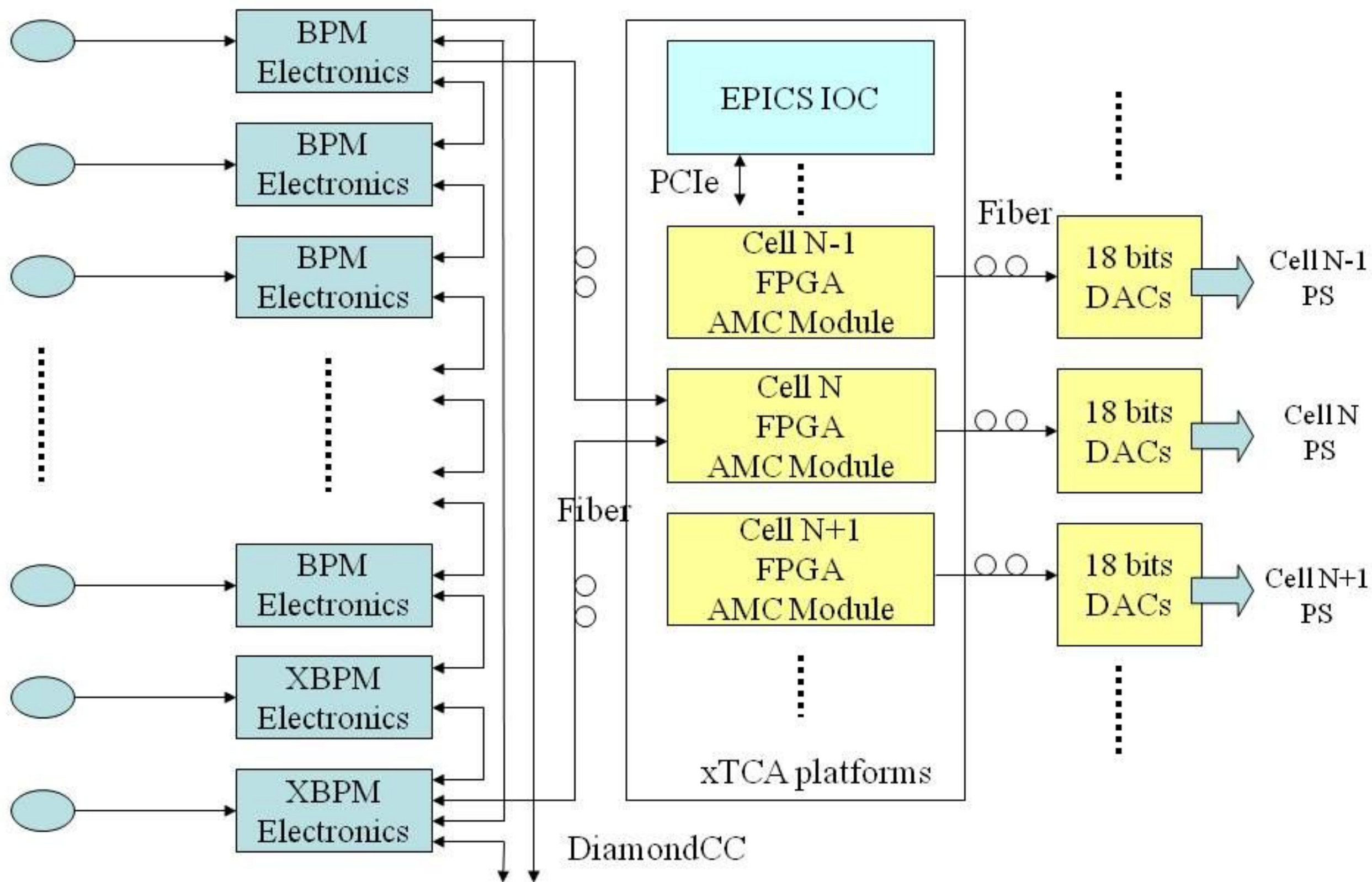
# Proposed Infrastructure for the TPS Orbit Feedback





# One of an Implementation Option

## $\mu$ TCA/aTCA/AMC + FPGA + DiamondCC + Remote DAC



# Post-mortem Diagnostic Supports

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- BPM electronics:
  - Post-mortem buffer (turn-by-turn)
  - Dedicated fast data capture nodes to capture for more than 5 seconds at 10 kHz rate.
- cPCI ADC module with post-mortem buffer:
  - Up to 10 msec time resolution for more than 5 seconds.
- Transient and waveform diagnostic:
  - High timing resolution ( $\sim$  nsec) with segmented sweep
  - multiple-trigger capability
- Beam trip trigger is planned to distribute via event system.



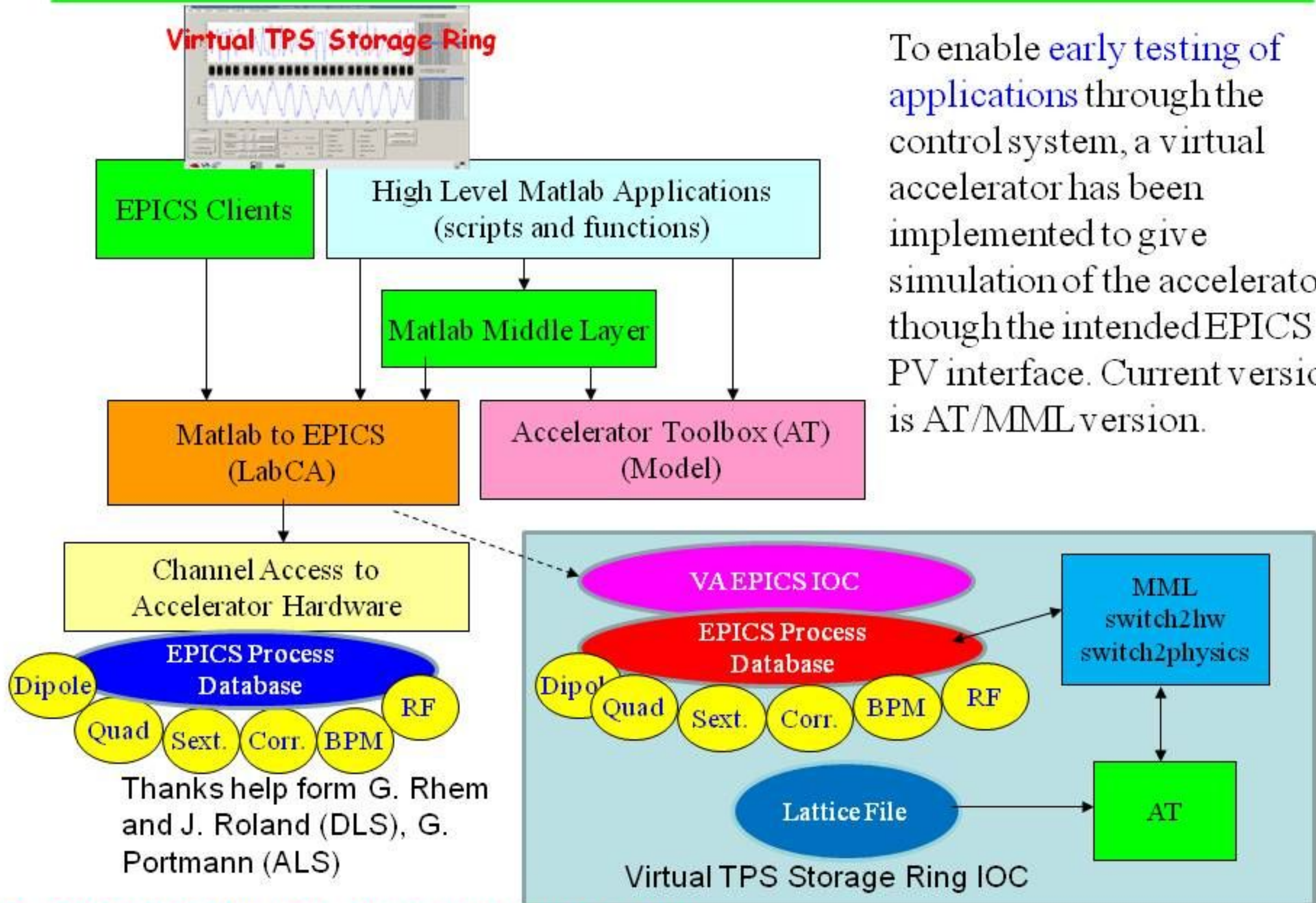
# Software Environment

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- Control system framework:  
EPICS toolkits
- High level physics applications:  
Matlab/Accelerator Toolkit/Matlab Middle Layer  
Setup virtual accelerator to support high level application  
development is underway
- Many items are still in study  
Relation database  
Technical system interface  
Documentation, E-log  
Machine status broadcasting: web, IPTV  
...etc.

# High Level Applications Interface

Virtual TPS Storage Ring



To enable early testing of applications through the control system, a virtual accelerator has been implemented to give simulation of the accelerators through the intended EPICS PV interface. Current version is AT/MML version.

Thanks help form G. Rhem and J. Roland (DLS), G. Portmann (ALS)



# Works in Proceed

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- Cultivate EPICS peoples.
- Define standard hardware, work out on EPICS Device/driver supports.
- Family of various clients and server tools of EPICS.
- Planning for various issues (name convention, networking, ...).
- Setup testbed in 2010 ~ 2011:
  - Training system
  - Various IOCs prototype
  - Various EPICS clients applications
  - RDBMS
  - OPI
- Work out a solid plans for the TPS control system:
  - Procurement, development, priority schedule, implementation, installation, commissioning, ...

# Summary

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- Standardization of hardware and software are in proceed.
- Work out EPICS device/driver support to various selection hardware is under way.
- Setup test-beds and dummy IOCs for evaluation and applications development is a short term goal.
- Economic and high performance design and implementation.



Thank You for Your Attention!