



Recent Progress of the RF and Timing System of XFEL/SPring-8

H. Maesaka, T. Ohshima, N. Hosoda, S. Matsubara,
K. Tamasaku, T. Fukui and Y. Otake: RIKEN/SPring-8
M. Musha: Univ. of Electro-communications

2009. 10. 13.

Outline

- X-ray Free Electron Laser (XFEL) project at SPring-8
- Design of the RF and timing system
 - Requirements
 - Design concept
 - Optical RF and timing distribution system
 - Precise low-level RF control system
- Water-cooled enclosure
 - Water-cooled 19-inch rack
 - Water-cooled optical cable duct
- Performance measurement
 - Optical system
 - Low-level RF system
- Summary

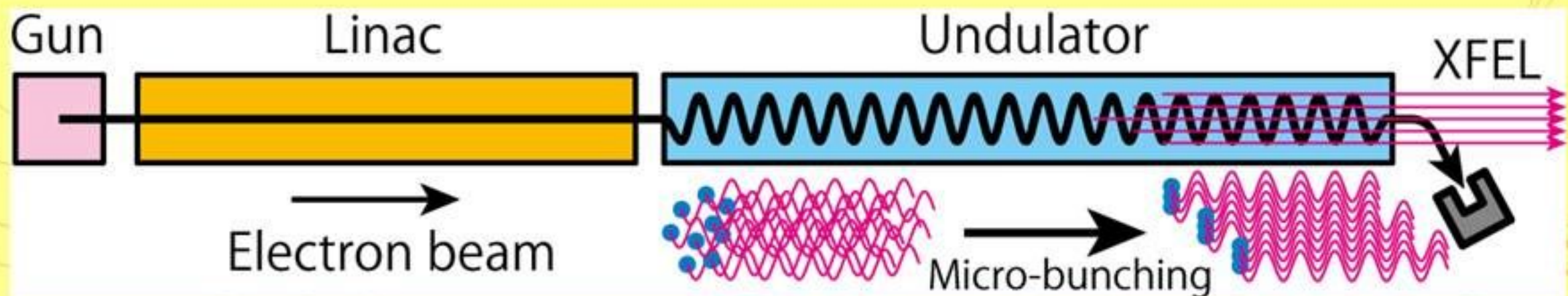


XFEL Project at SPring-8

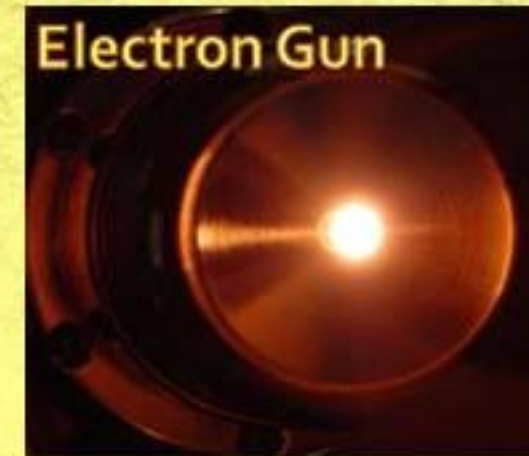


X-ray Free Electron Laser (XFEL)

- To generate coherent and intense x-rays.
 - For life sciences and material sciences etc.
- SASE process
 - Self-Amplified Spontaneous Emission
 - No optical cavity
 - Long undulator beamline is needed
 - To give rise to the interaction between electrons and x-rays.
- Low-emittance and high-peak-current beam are required.



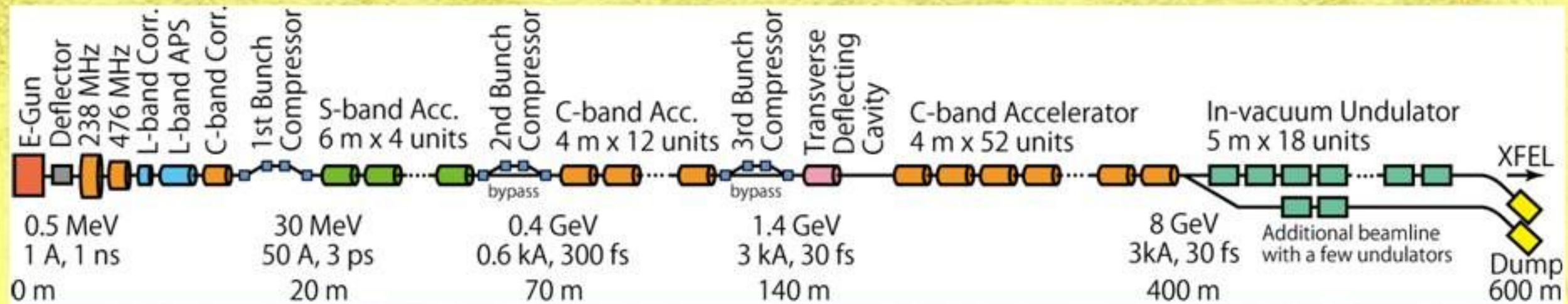
Project Overview



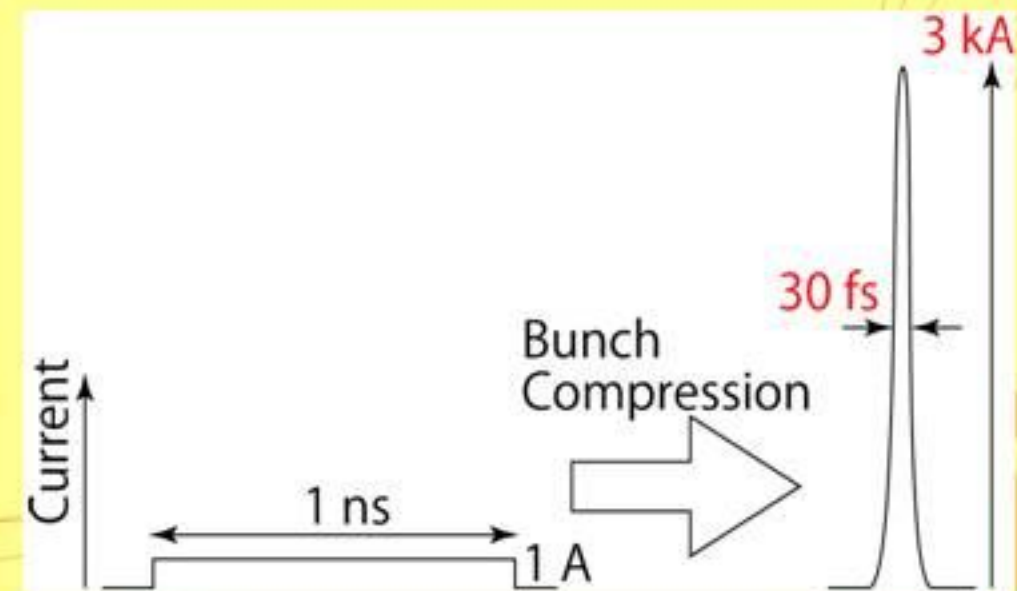
- X-ray wavelength: $< 0.1 \text{ nm}$
- Beam energy: 8 GeV
- Key technologies
 - Low-emittance thermionic electron gun: $0.6 \pi \text{ mm mrad}$
 - High-gradient C-band accelerator: 35 MV/m
 - Short-period in-vacuum undulator: $\lambda_u = 18 \text{ mm}$
- First FEL light will be delivered in 2011.



XFEL Machine Layout

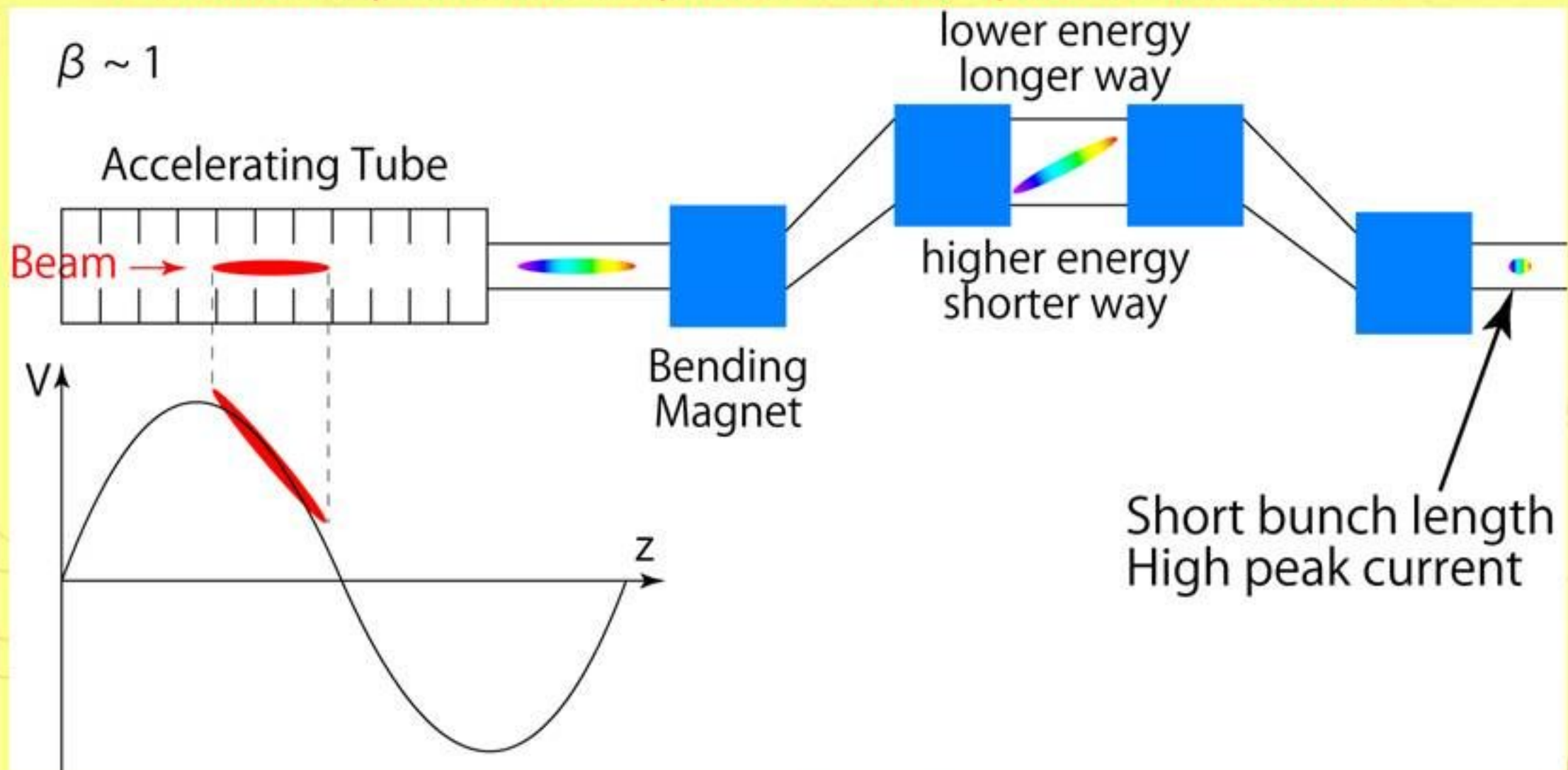


- 8GeV linear accelerator
 - 238 MHz, 476 MHz, L-band (1428 MHz), S-band (2856 MHz) and C-band (5712 MHz)
- Key parameters of SASE-FEL
 - Normalized slice emittance: $0.7 \pi \text{ mm mrad}$
 - Peak current: 3 kA
- Slice emittance
 - Accelerate without emittance growth
- Peak current
 - Compress the longitudinal bunch structure
- Bunch compression
 - Velocity bunching in the low energy region
 - Three bunch compressors (magnetic chicane)
 - Bunch length: $1 \text{ ns} \rightarrow 30 \text{ fs}$ (FWHM)
 - Peak current: $1 \text{ A} \rightarrow 3 \text{ kA}$



Bunch Compressor

- In a magnetic chicane, low-energy electrons travel longer way than high-energy electrons.
 - Accelerator gives an energy chirp to the beam.
 - Energy of head electrons is made lower than that of tail electrons.
 - Strength of the energy chirp is very sensitive to the compression ratio.
- Precise RF phase and amplitude control system is demanded.



Design of the RF and Timing System



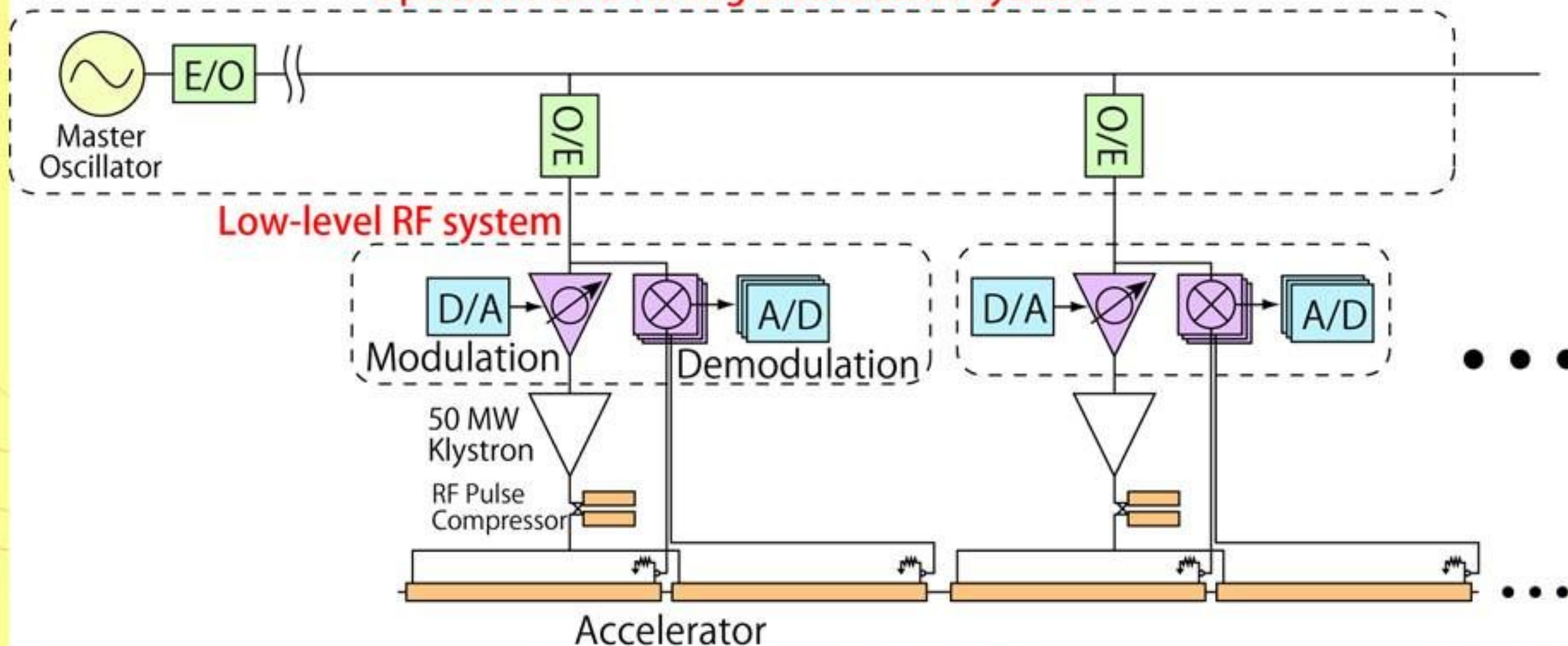
Requirements for the Timing System

- Should be as stable as possible!
 - This system provides the timing standard of the whole system.
- **Timing stability** of the acceleration field
 - Phase stability: **0.1 degree (rms) of 5712 MHz**
 - Equivalent to **50 fs (rms)**
- **Amplitude stability** of the acceleration field
 - **0.01% (rms)**
- Many RF signals are needed
 - 5712MHz, 2856MHz, 1428MHz, 476MHz, 238MHz and Trigger pulse
- Long transmission length
 - Accelerator: **400 m**
 - From the gun to the experimental hall: **700 m**
 - Some experiments (pump-probe etc.) demand a precise time reference.

Design Overview

- **Optical RF and timing distribution system**
 - Attenuation of an optical fiber is much smaller than a metal cable
 - Need to stabilize the fiber length ($1 \mu\text{m} = 5 \text{ fs}$)
- **Low-level RF control system**
 - IQ (In-phase and Quadrature) modulation and demodulation
 - High-speed D/A and A/D converters for baseband signals

Optical RF and Timing Distribution System



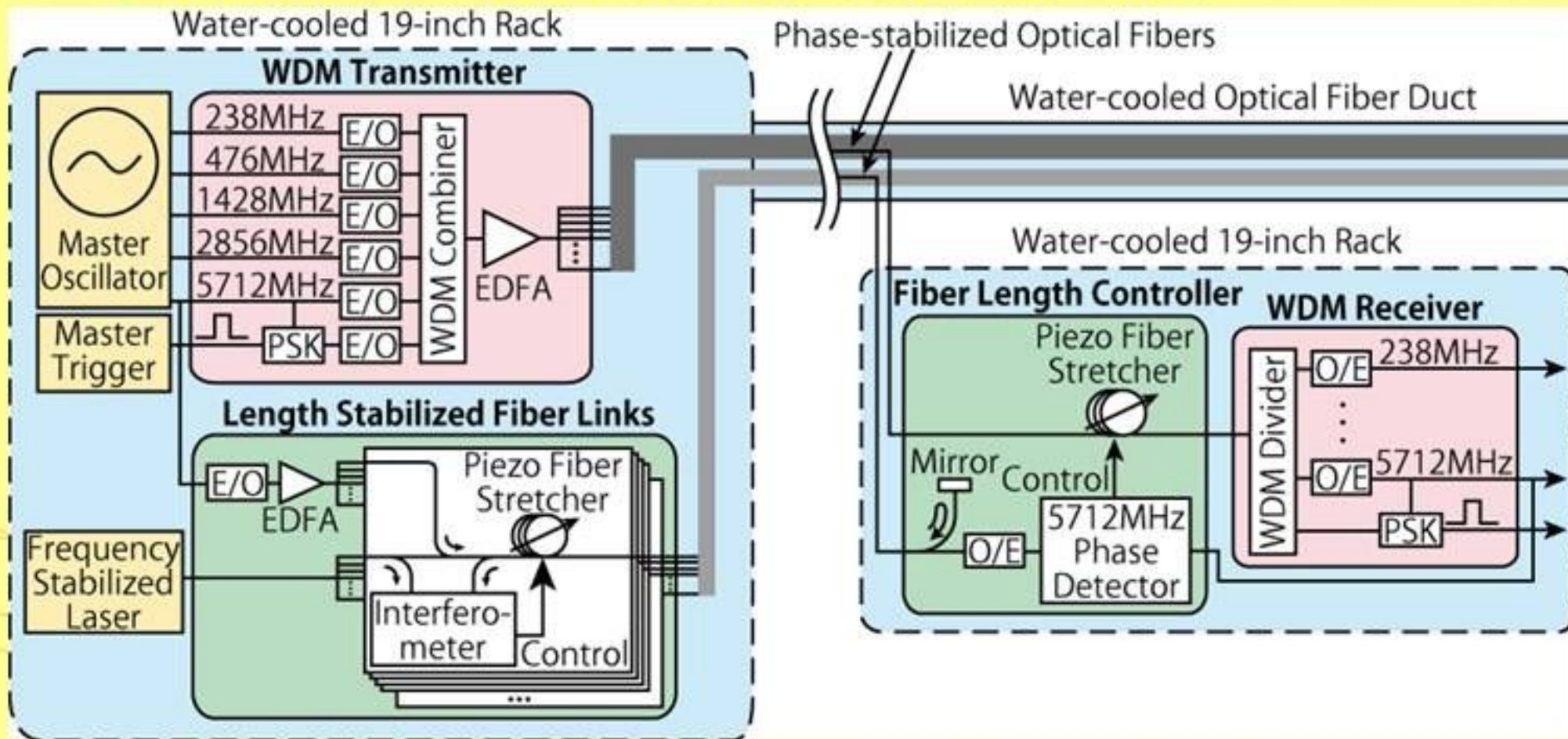
Design Concept

- Eliminate fluctuation sources as much as possible before applying active feedback loops.
 - Select stable components (ICs, cables, passive elements ...)
 - Small temperature coefficient
 - Low-noise electric device
 - Stabilize the temperature of each component.
 - Provide low-noise electric power.
 - Reduce vibration of cables
- If there still remain any fluctuations, we use active feedback loops.



Optical RF and Timing Distribution System

- **Wavelength Division Multiplexing (WDM) technique**
 - To combine all signals to one fiber.
 - **Phase-stabilized optical fiber** (~ 1 ps/km/K)
 - **Water-cooled 19-inch rack and water-cooled optical fiber duct**
 - To reduce the thermal drift of the RF phase and amplitude
 - **Length-stabilized fiber link**
 - Additionally prepared for the phase reference.
 - Michelson interferometer monitors the fiber length.
 - Fiber stretcher controls the fiber length.
 - Time drift of the WDM fiber is controlled at the receiver side.
- Passive
~100fs stability
- Active
~10fs stability

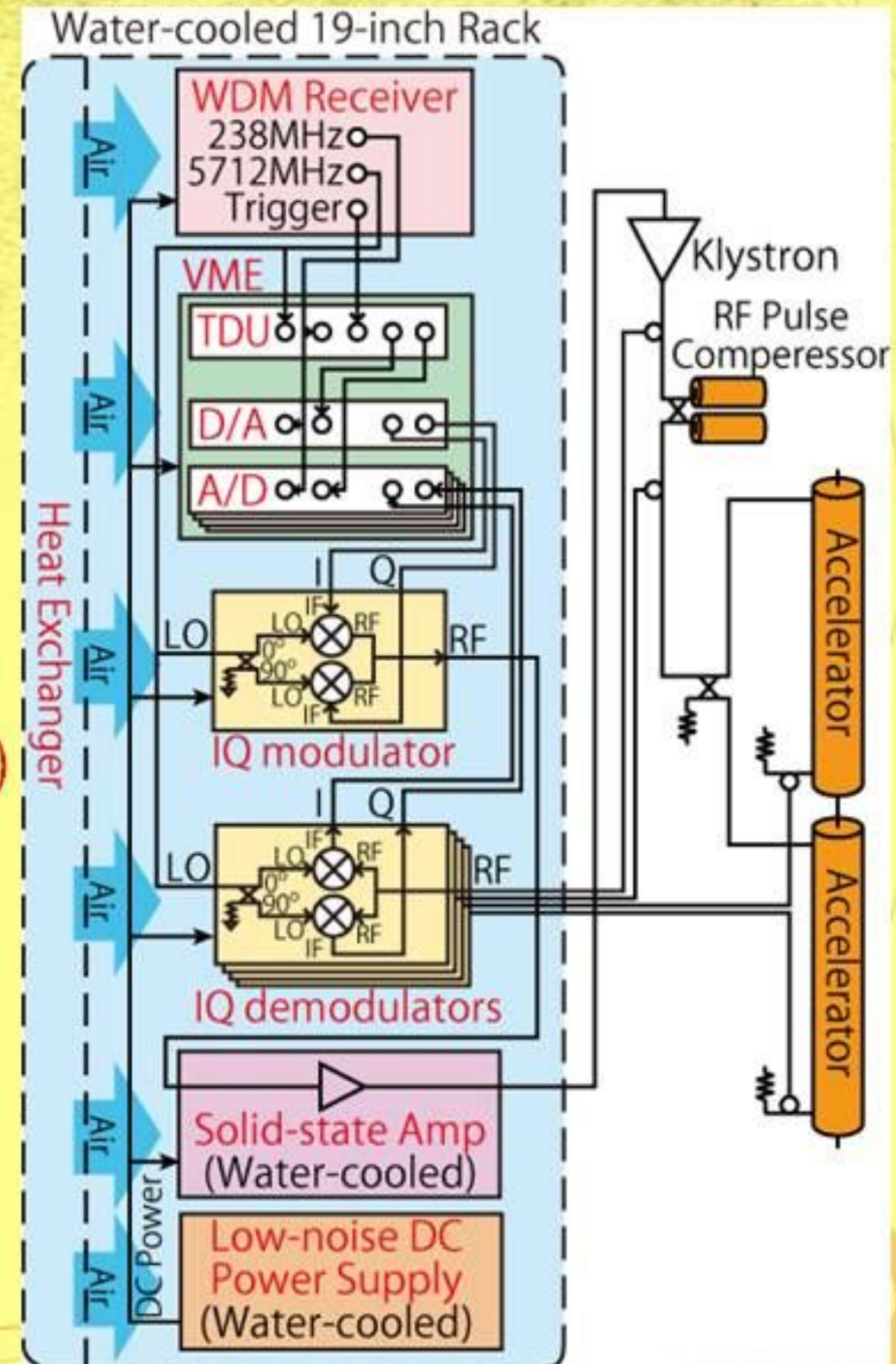


Low-level RF Control System

- **IQ modulator** produces the acceleration RF signal with appropriate phase and amplitude.

$$V(t) = I(t) \cos(\omega t) + Q(t) \sin(\omega t)$$

- **IQ demodulator** detects the phase and amplitude of the acceleration RF.
- Baseband waveforms are processed by **VME high-speed D/A and A/D converter boards**.
 - Sampling rate: **238 MSPS**
 - Resolution: **14 bits (D/A)** and **12 bits (A/D)**
- All modules are enclosed in a **water-cooled 19-inch rack**.
 - To reduce the thermal drift.
- DC power is distributed from a **low-noise power supply**
 - Clean and stable power
 - Small heat load for the 19-inch rack



Water-cooled Enclosure

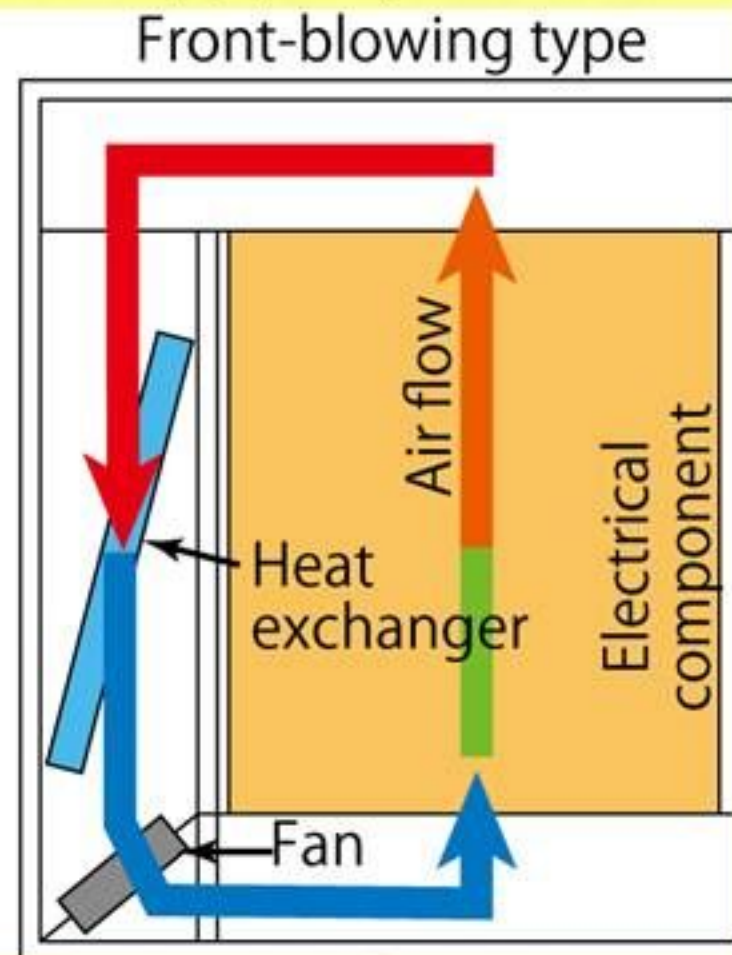
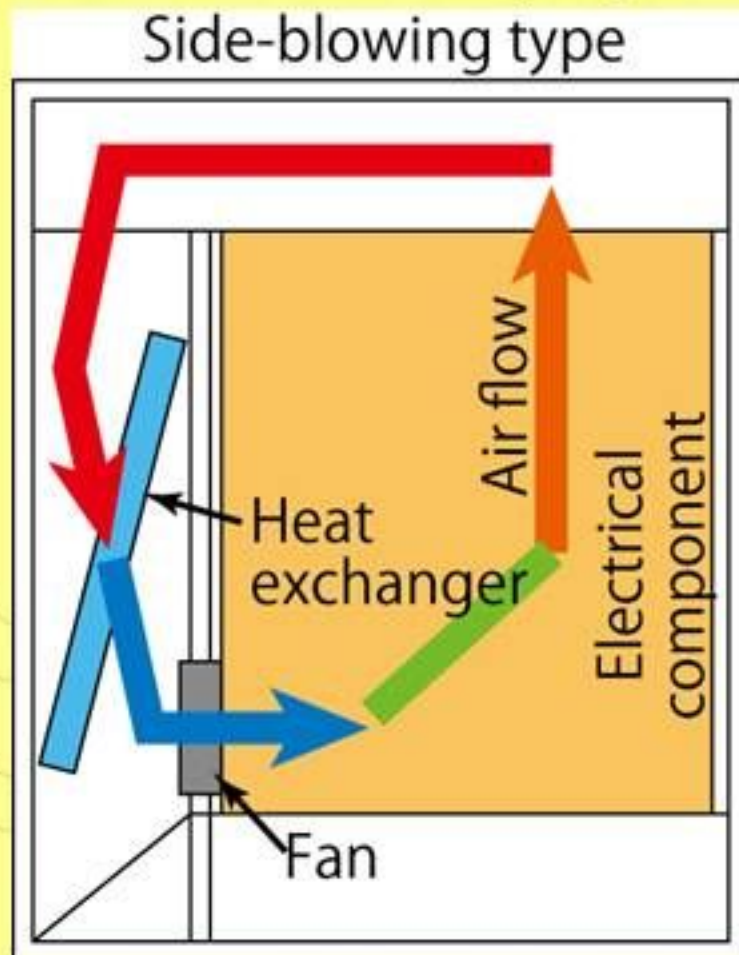
for the temperature stabilization

One of the features of our design



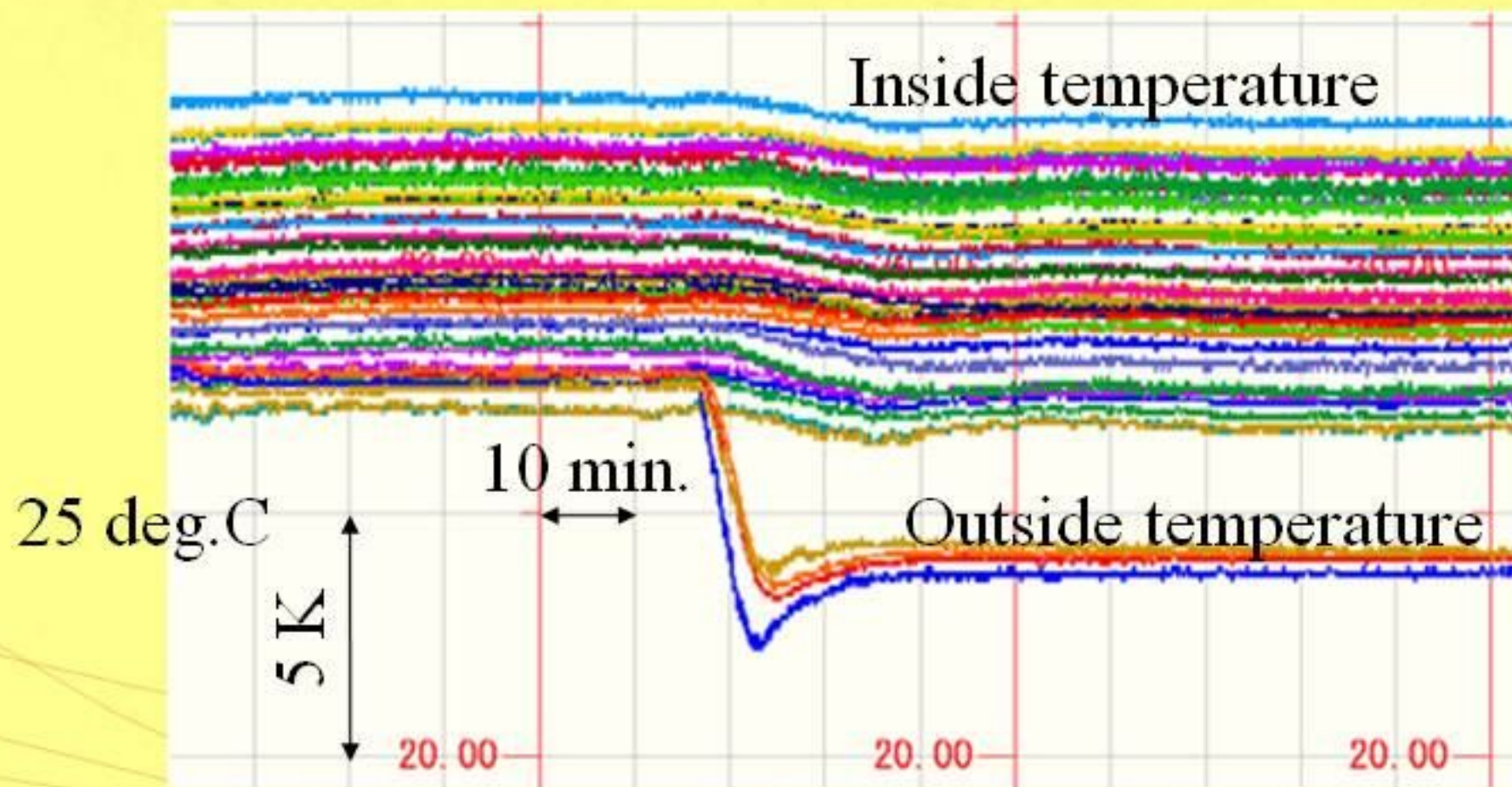
Water-cooled 19-inch Rack

- Heat exchanger cools the circulating air.
- Temperature stability of the cooling water is 0.4 K (p-p), typically 0.2 K (p-p)
- Side-blowing type
 - Not to shake cables around the front panel.
 - Cable vibration is critical in the femto-second region!
 - VME boards are horizontally mounted.
- Front blowing-type
 - Other circuits (magnet power supply etc.)



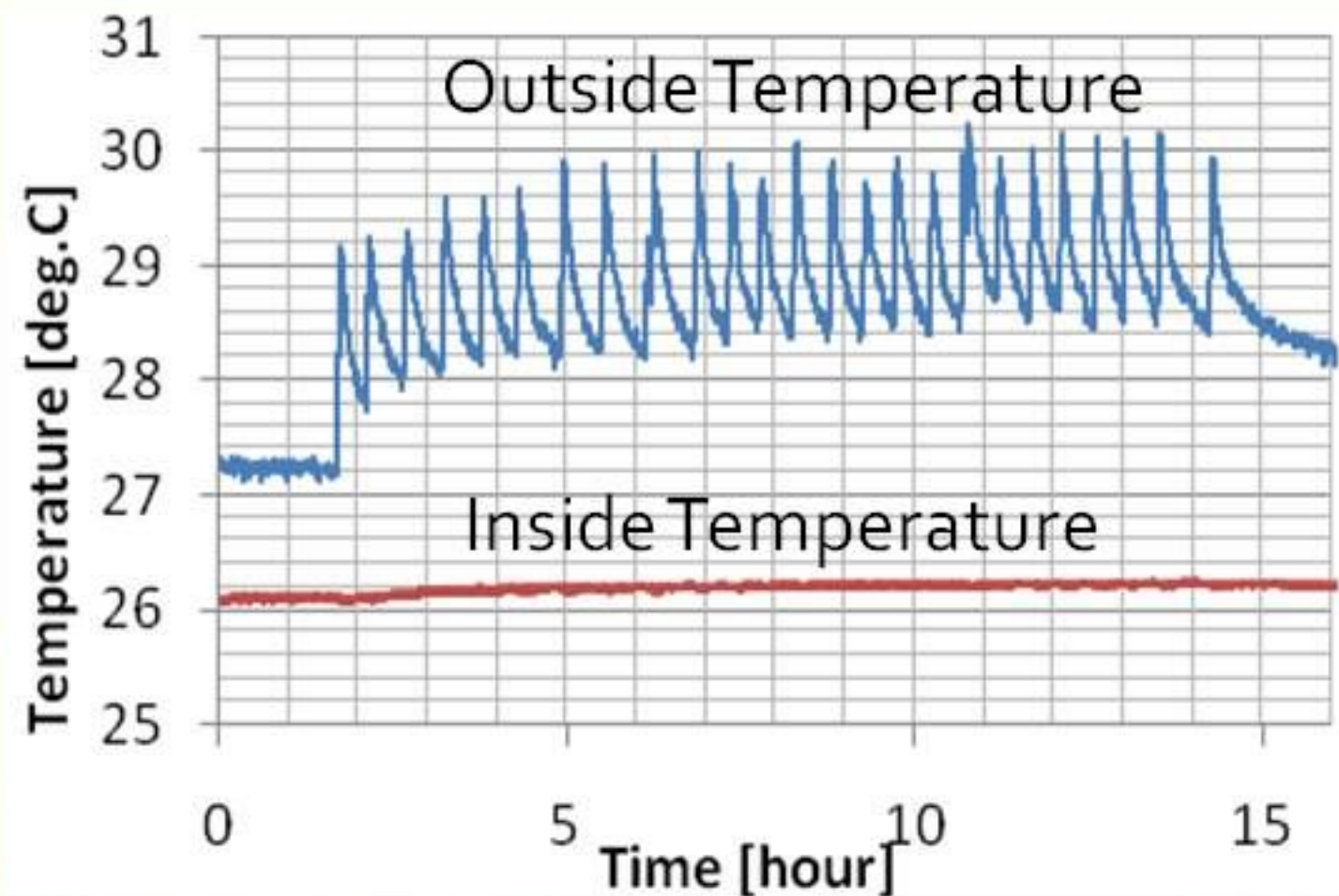
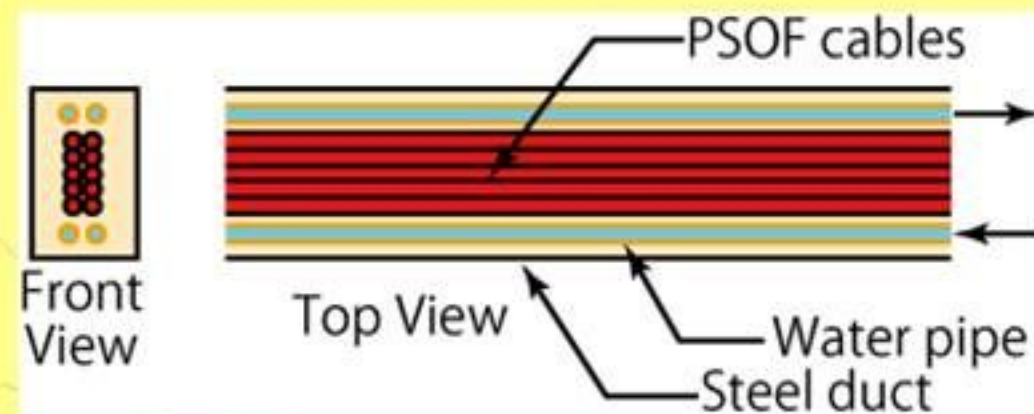
Temperature Stability of the Rack

- We tested the temperature stability of the water-cooled rack.
- We intentionally decreased the **water temperature by 0.4 K** and **outside temperature by 4 K** at the middle of the measurement.
- Inside temperature drift was **0.42 K**.
 - Appropriately follows the water temperature.
 - Almost no effect from outside.



Water-cooled Optical Fiber Duct

- Optical fiber temperature is stabilized by cooling water.
- Stability measurement
 - Water temperature fluctuation: 0.24 K (p-p)
 - Outside temperature fluctuation: 3.4 K (p-p)
- Inside temperature is regulated within 0.12 K (p-p)
 - < 200 fs (p-p) for 1km phase-stabilized optical fiber (PSOF)



Photograph of the Klystron Gallery

- A part of the RF and timing system has been installed.

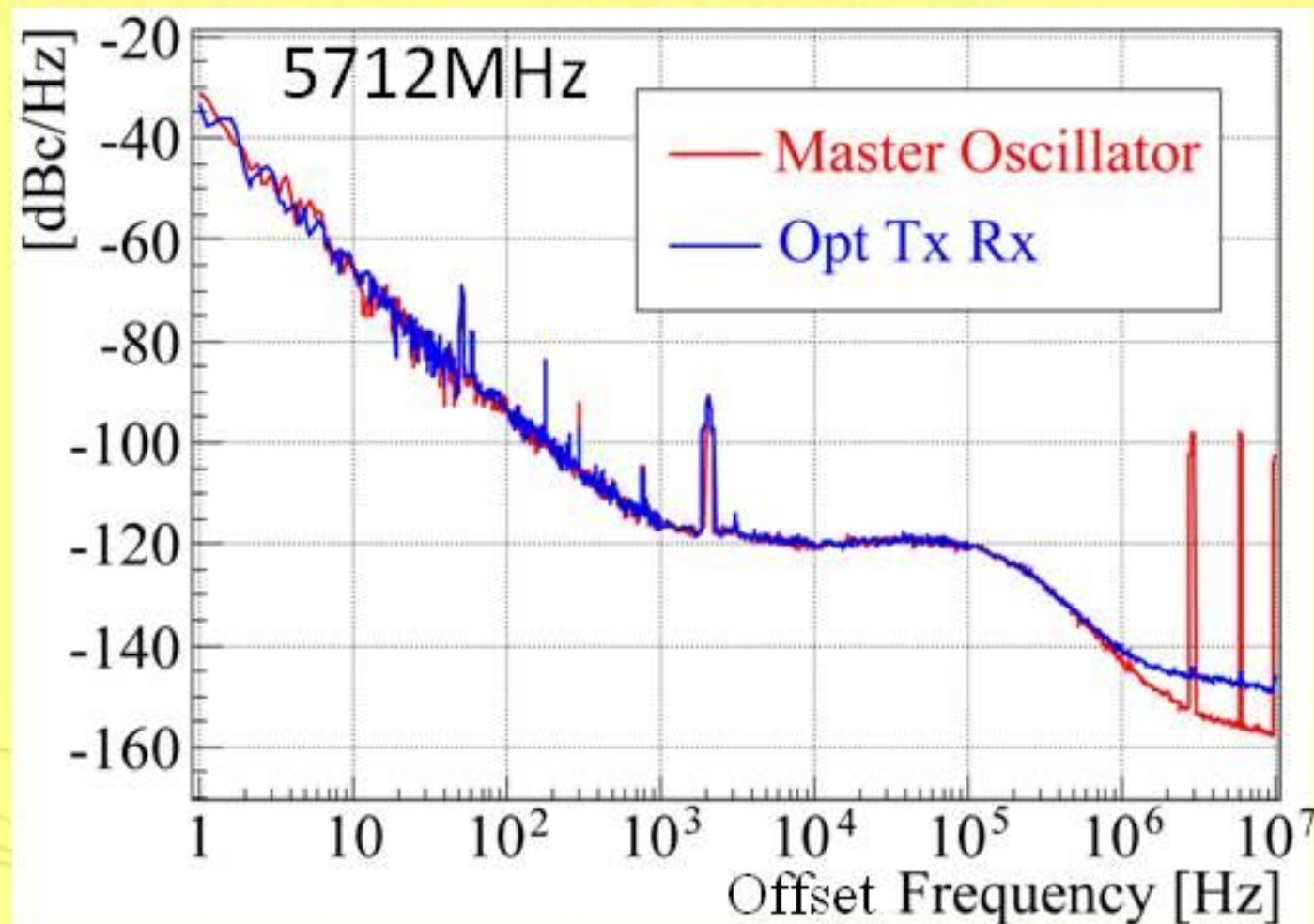


Performance Measurement of the RF and Timing System



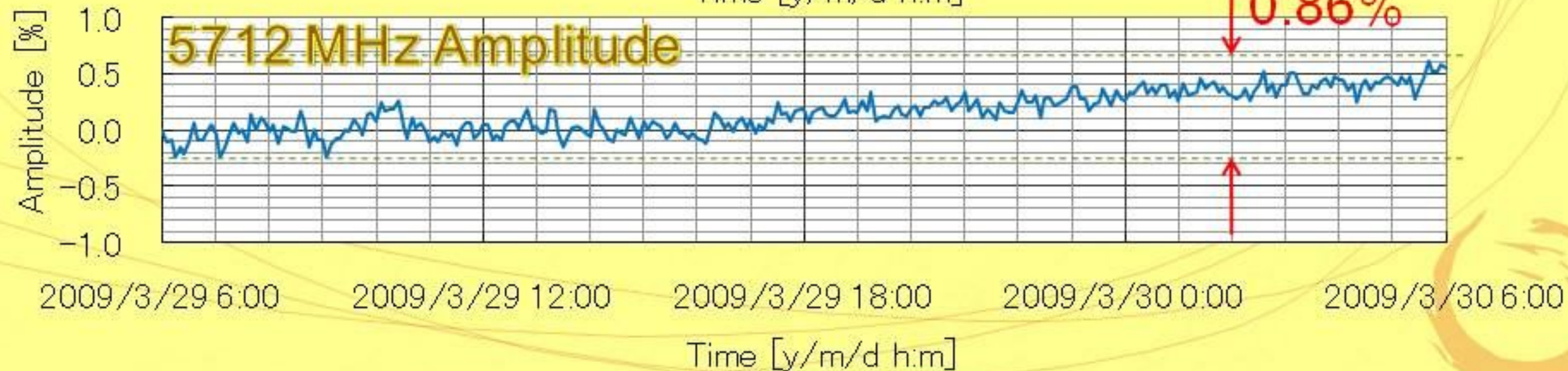
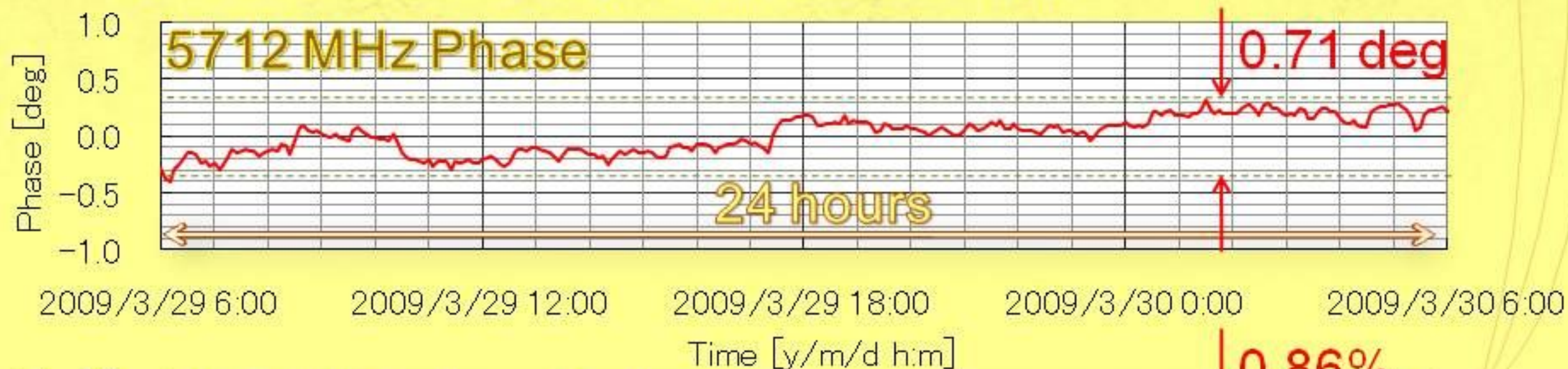
SSB Phase Noise

- We measured the SSB (Single Side Band) phase noise of the optical RF and timing distribution system.
 - Master oscillator itself
 - After transmission with the optical distribution system.
- No deterioration in < 1 MHz
- A little degradation above 1 MHz, but small enough (~ 7 fs)
- Time jitter is estimated to be **30 fs (rms)**



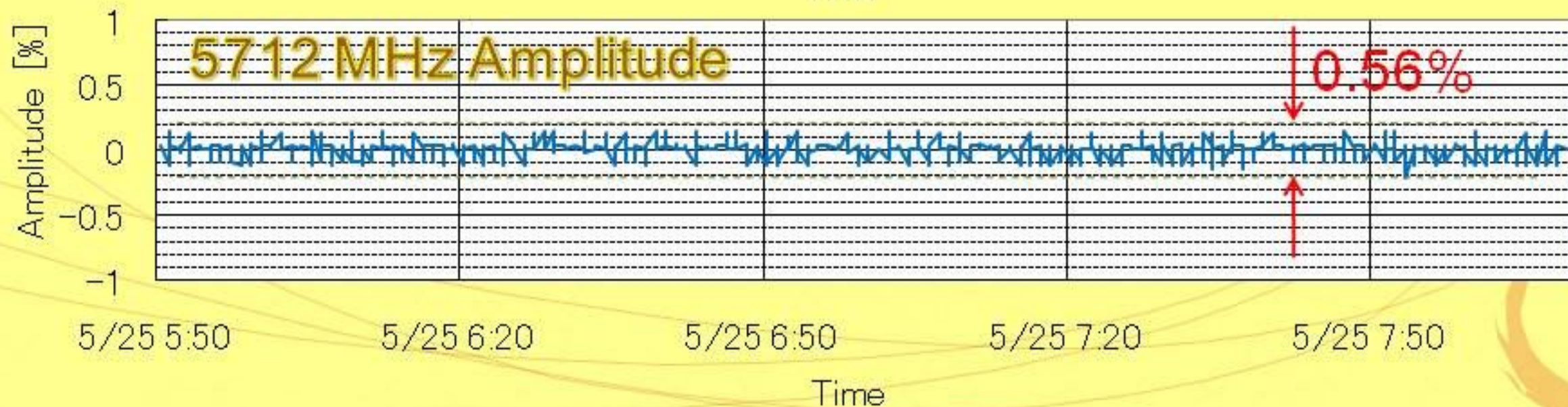
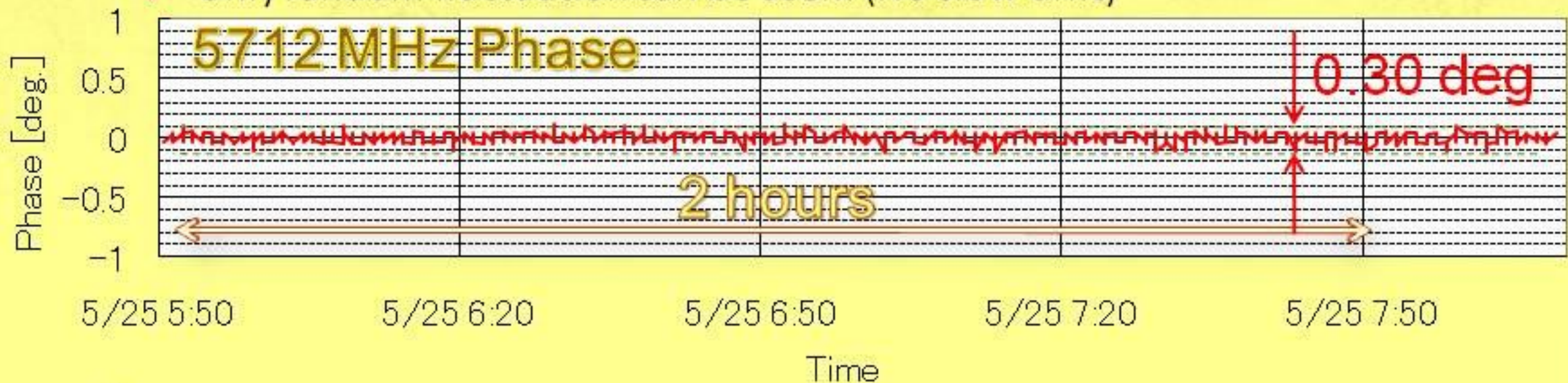
Stability of the Optical System

- Optical system was enclosed in a thermostatic chamber.
- Measurement period: 24 hours
- Temperature stability: 0.7 K (p-p)
- Phase stability: 0.71 degree (p-p)
- Amplitude stability: 0.86% (p-p)
- Drifts of detectors: 0.2 degree (p-p) and 0.06% (p-p)



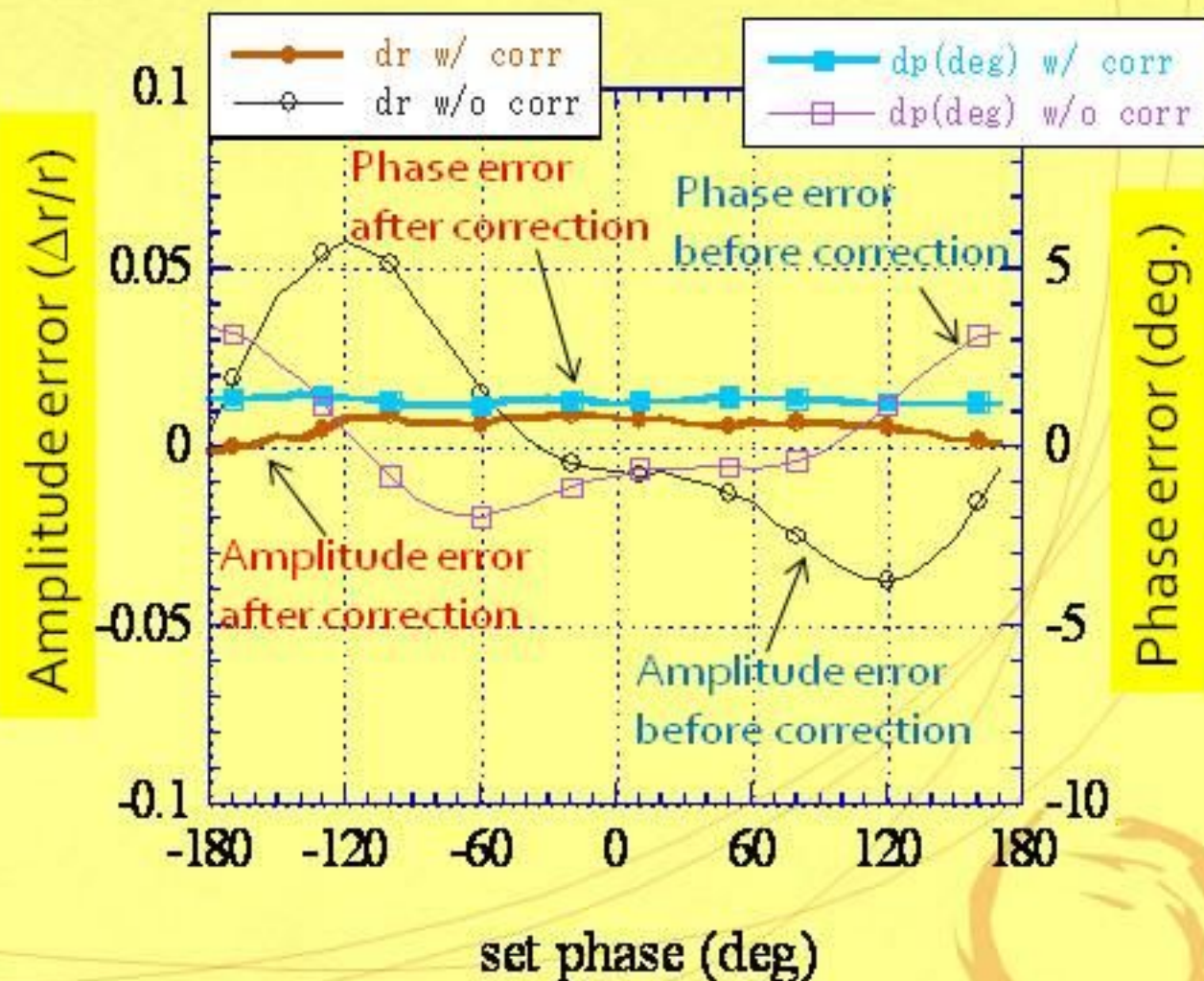
Stability of the Low-level RF System

- VME-D/A → IQ modulator → Solid-state Amp. → IQ demodulator → VME-A/D
- Temperature stability: 0.3 K (p-p)
- Phase stability: 0.30 degree (p-p)
- Amplitude stability: 0.56% (p-p)
 - Resolution limit of 12-bit A/D converter.
 - Only random fluctuation can be seen. (No slow drift)



Error Correction of IQ modulator

- IQ modulator and demodulator have some errors.
 - Phase: ~ 5 degrees (p-p)
 - Amplitude: $\sim 10\%$ (p-p)
 - These errors disturb the fine tuning of the accelerator.
 - Cause an interference between the feedback controls of RF phase and amplitude
- The error itself does not drift
 - Can be corrected by software.
- After correction
 - Phase error: 0.3 degree (p-p)
 - Amplitude error: 1% (p-p)
- Details are presented by T. Ohshima (WEP023).



Summary (1/2)

- XFEL/SPring-8

- Generates coherent and intense x-rays with 0.1 nm wavelength region.

- Requirements for the acceleration RF field

- Phase stability: 0.1 deg. (rms) of 5712 MHz (~ 50 fs)
- Amplitude stability: 0.01% (rms)

- Precise RF and Timing system

- Optical RF and timing distribution system
 - WDM technique and Length-stabilized fiber link
- Low-level RF control system
 - IQ modulator and demodulator



Summary (2/2)

- **Temperature regulation**
 - Water-cooled 19-inch rack
 - Water-cooled optical fiber duct
 - Both enclosures can reduce the temperature fluctuation within **0.4 K (p-p)**.
- **Phase stability**
 - Optical system: **0.71 degree (p-p)** of 5712 MHz
 - Low-level RF system: **0.30 degree (p-p)** of 5712 MHz
 - Sufficient for XFEL/SPring-8
- **Amplitude stability**
 - Optical system: **0.86% (p-p)**
 - Low-level RF system: **0.56% (p-p)**
 - This drift is suppressed by a klystron that is operated at saturation point.

Acknowledgements

- We thank
 - **Mitsubishi Electric TOKKI System**
 - **Kinden**
 - **And many other companies**for their grate efforts to develop the precise RF and timing system.
- Thank you for your attention!

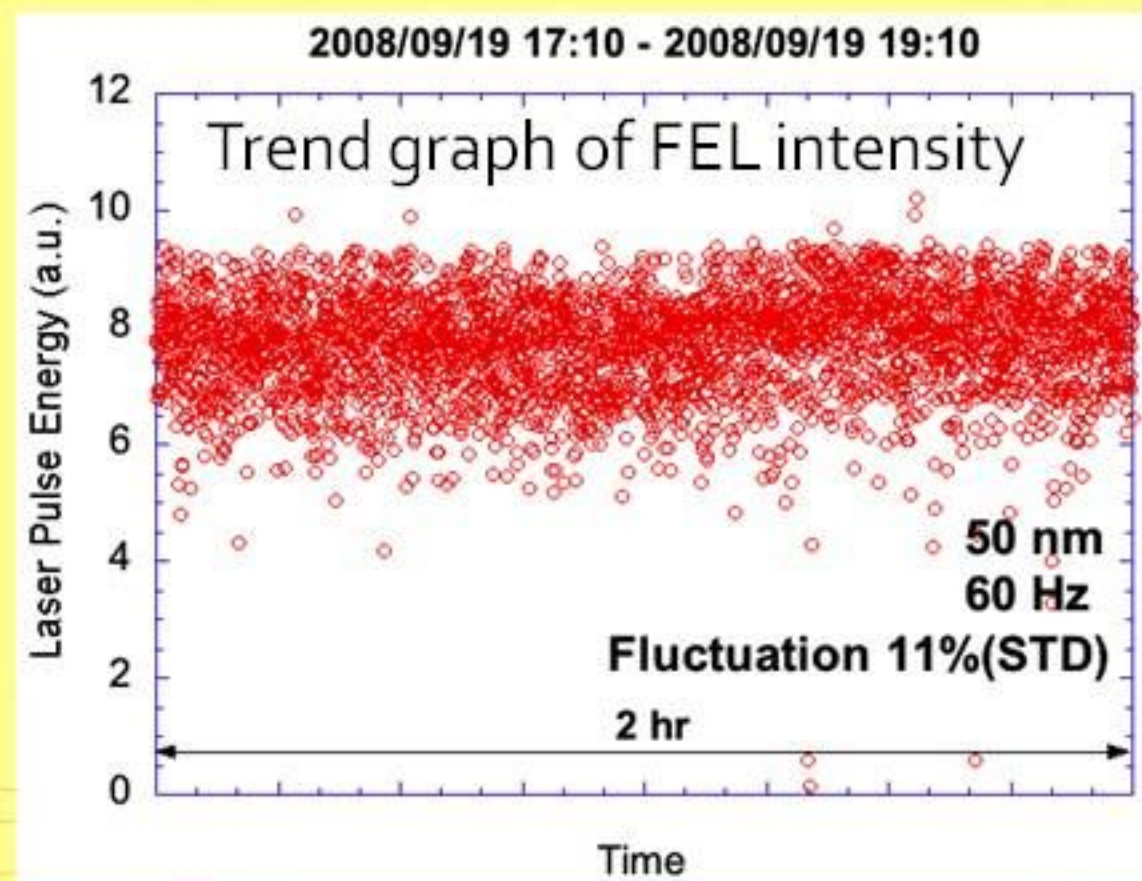
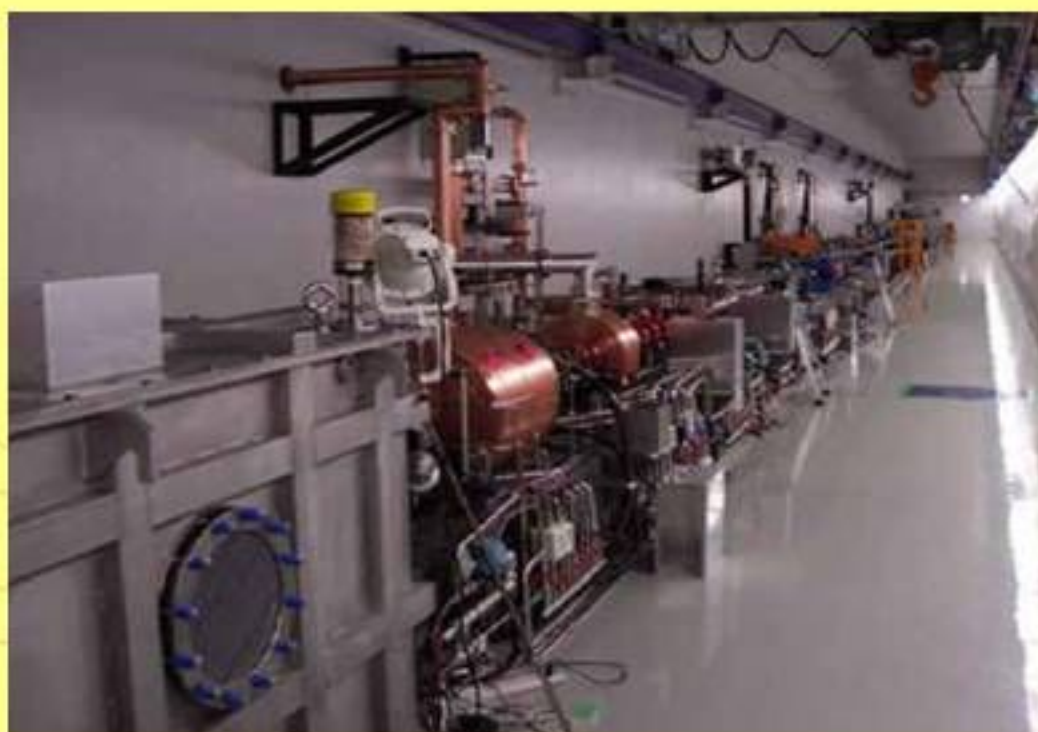


Backup



SCSS Test Accelerator

- Extreme ultraviolet (EUV) FEL facility
 - Wavelength: 50 – 60 nm for saturated output
 - Beam energy: 250 MeV
- Saturated EUV laser light has been stably generated since 2006.

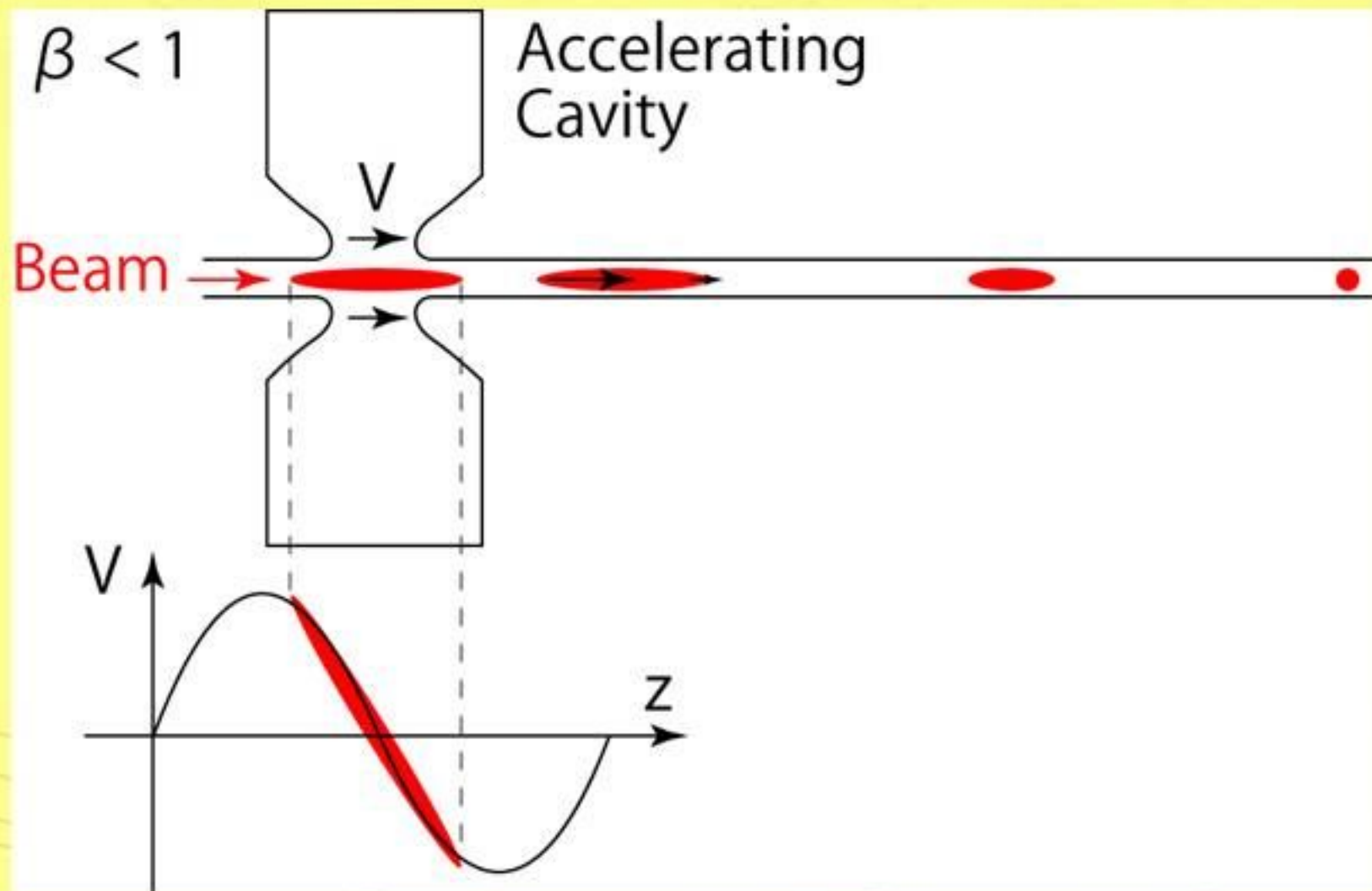


XFEL Machine Parameters

Beam Energy	8 GeV
Bunch Charge	0.3 nC
Normalized Slice Emittance	0.7π mm mrad
Repetition Rate	60 pps maximum
Peak Current	3 kA
Bunch Length	30 fs (FWHM)
Beam Radius	40 mm (RMS)
Undulator Period	18 mm
Undulator K-value	2.2 maximum
Undulator Gap	3 mm minimum
Number of Periods	$275 \times 18 = 4950$

Velocity Bunching

- For a low-energy beam ($\sim 1\text{MeV}$)
- Head electrons are decelerated and tail electrons are accelerated by an accelerating cavity.
- Tail electrons approach head electrons.



Peak Current and FEL Gain

FEL parameter

Peak current

$$\rho = \left[\frac{I_e \gamma \lambda^2}{16\pi I_A \sigma_x \sigma_y} \left(\frac{K[JJ]}{1 + K^2} \right)^2 \right]^{1/3}$$

FEL gain length

$$L_{G1D} = \frac{\lambda_u}{4\pi\sqrt{3}\rho}$$

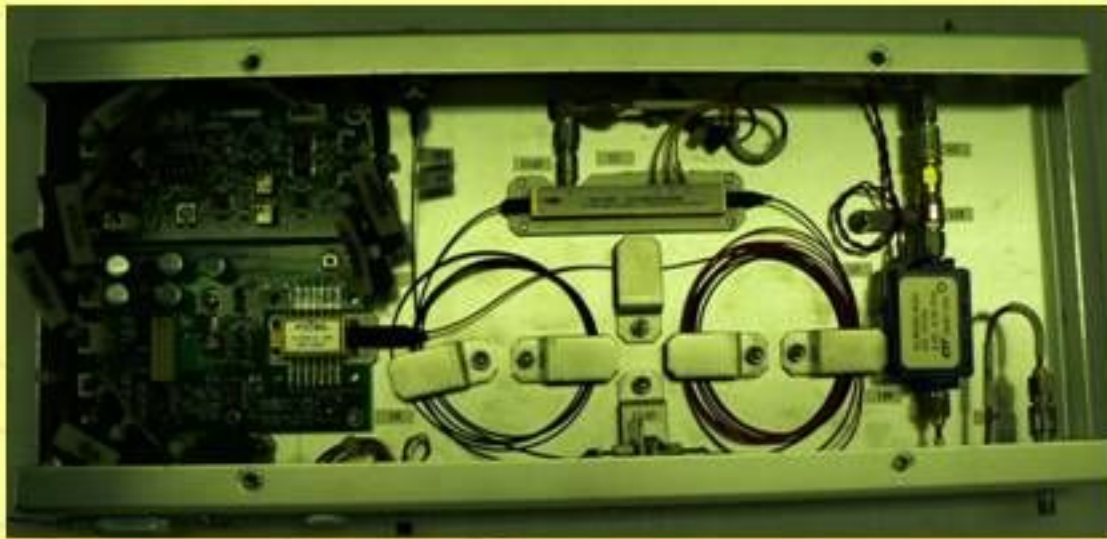
FEL power growth

$$P_{FEL} \propto \exp(\alpha \cdot L_G)$$



E/O and O/E Converters

- E/O Converter
 - Light source: DFB-LD (Distributed FeedBack Laser Diode)
 - LiNbO₃ Mach-Zehnder modulator
- O/E Converter
 - Fast photo-diode

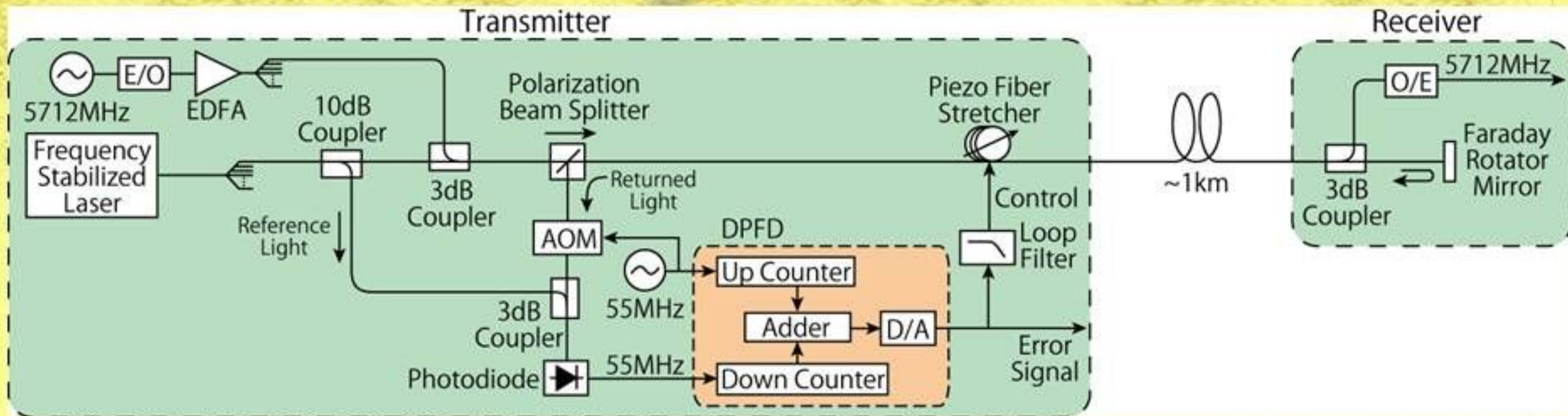


E/O Converter



O/E Converter

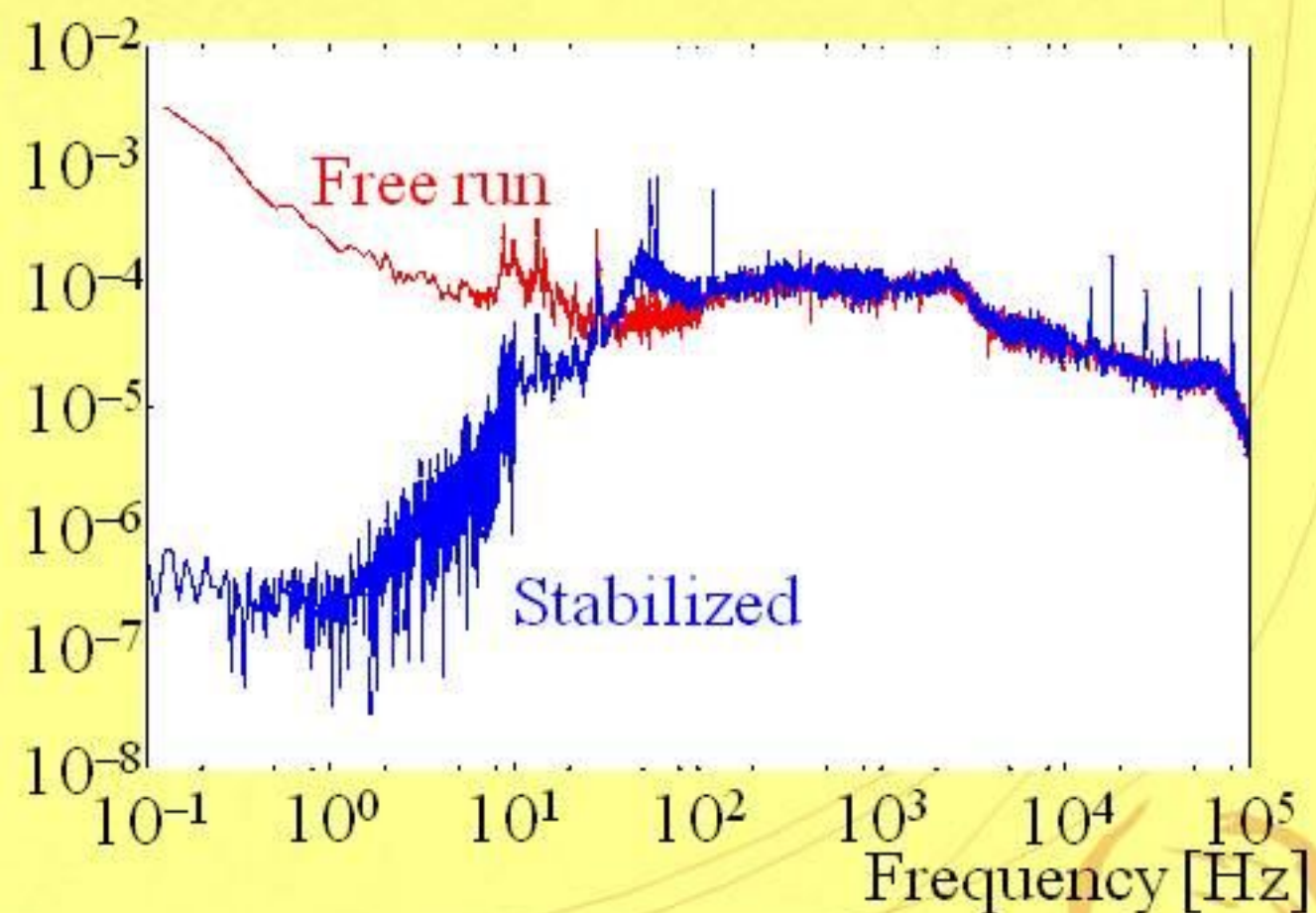
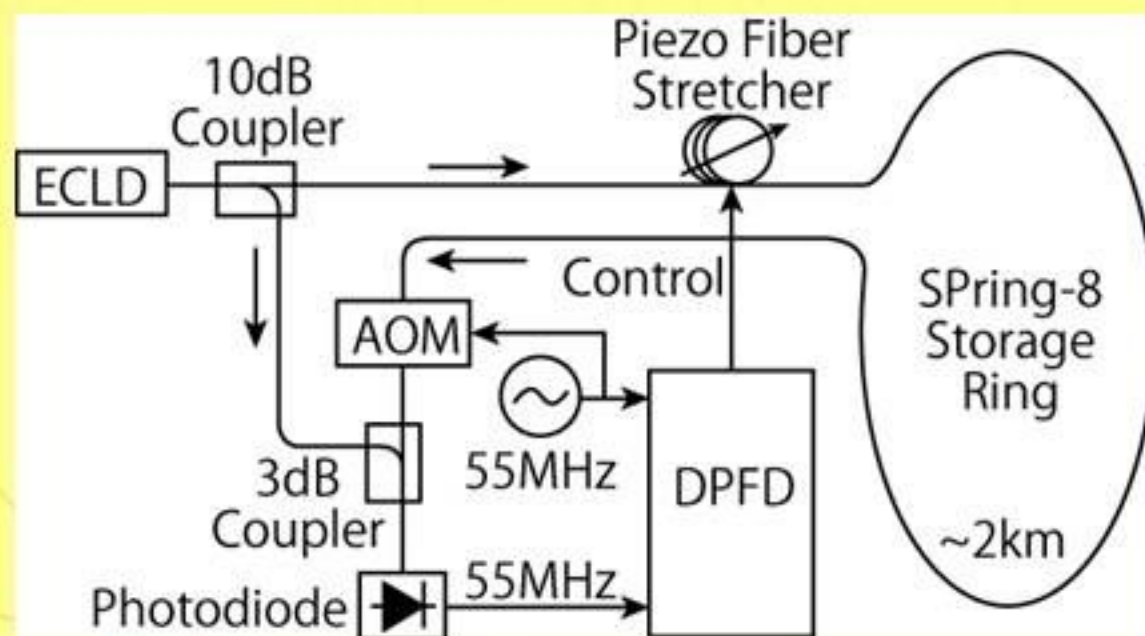
Fiber Length Stabilization



- Frequency-stabilized laser
 - Length standard
 - Frequency is locked to C_2H_2 absorption line.
- Transmitted light is returned by a Faraday rotator mirror.
- Polarization beam splitter discriminates the transmitted light and the returned light.
- Returned light is fed into an interferometer to monitor the fiber length.
 - 55MHz Acousto-optic modulator (AOM) enables a heterodyne detection of the optical phase.
 - Digital phase frequency discriminator (DPFD) for the phase detection.
- Piezo-electric fiber stretcher controls the fiber length.

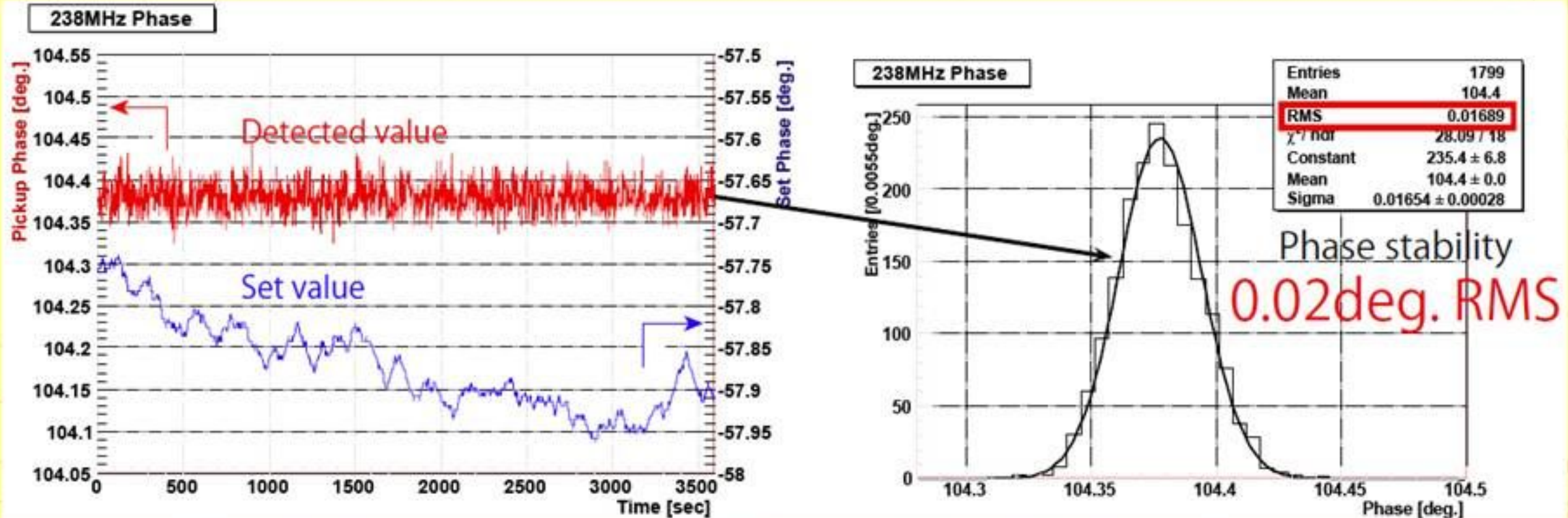
Fiber Length Stabilization Experiment

- We tested the fiber length stabilization system by using an optical fiber along the SPring-8 storage ring.
- Length fluctuation below 30 Hz was suppressed to 1 μm level.



PID Feedback Loop

- RF phase and amplitude detected by the IQ demodulator are fed back to the IQ modulator.
- PID (Proportional-Integral-Differential) algorithm
- Phase stability: **0.02 degree** rms for 238 MHz
- Amplitude stability: **0.03%** rms for 238 MHz



Stability of the Optical System

